

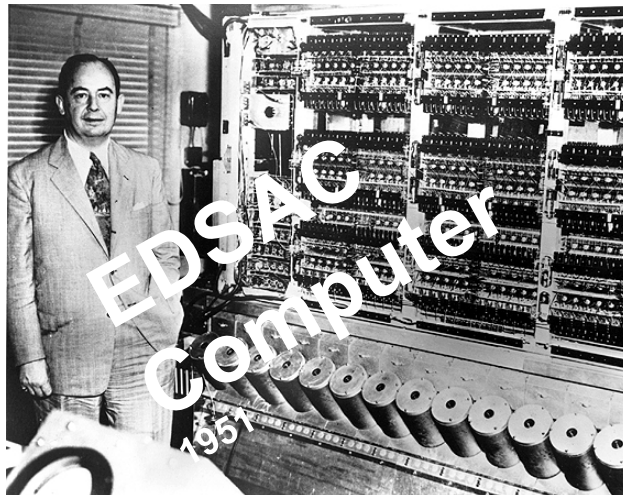
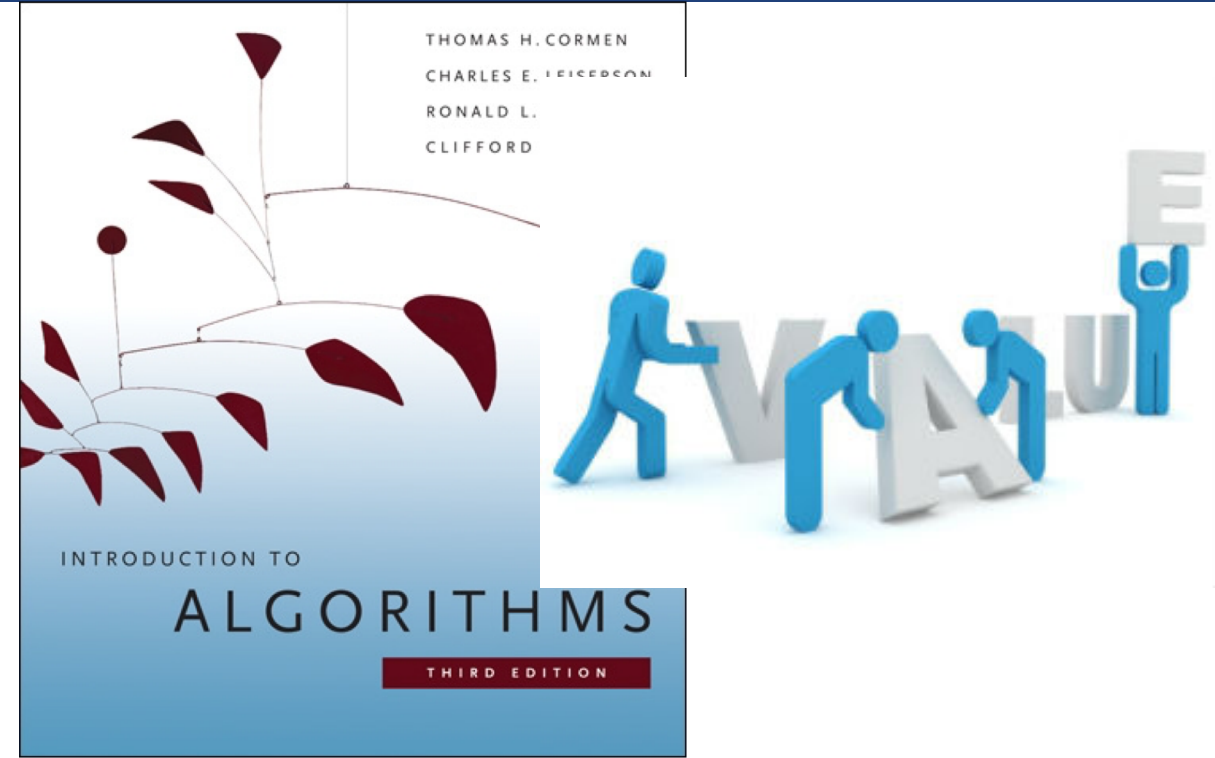


# Robust algorithmics - a foundation for science?!

**Joachim M. Buhmann**

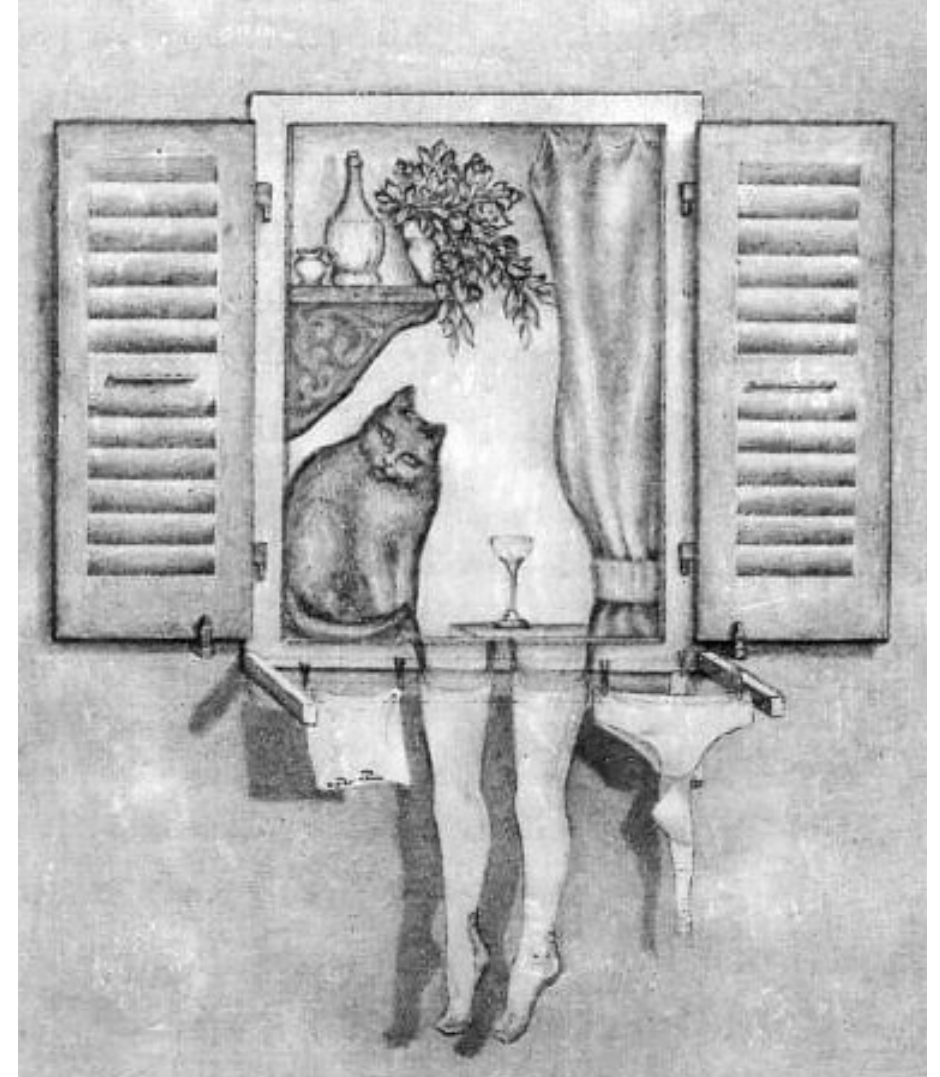
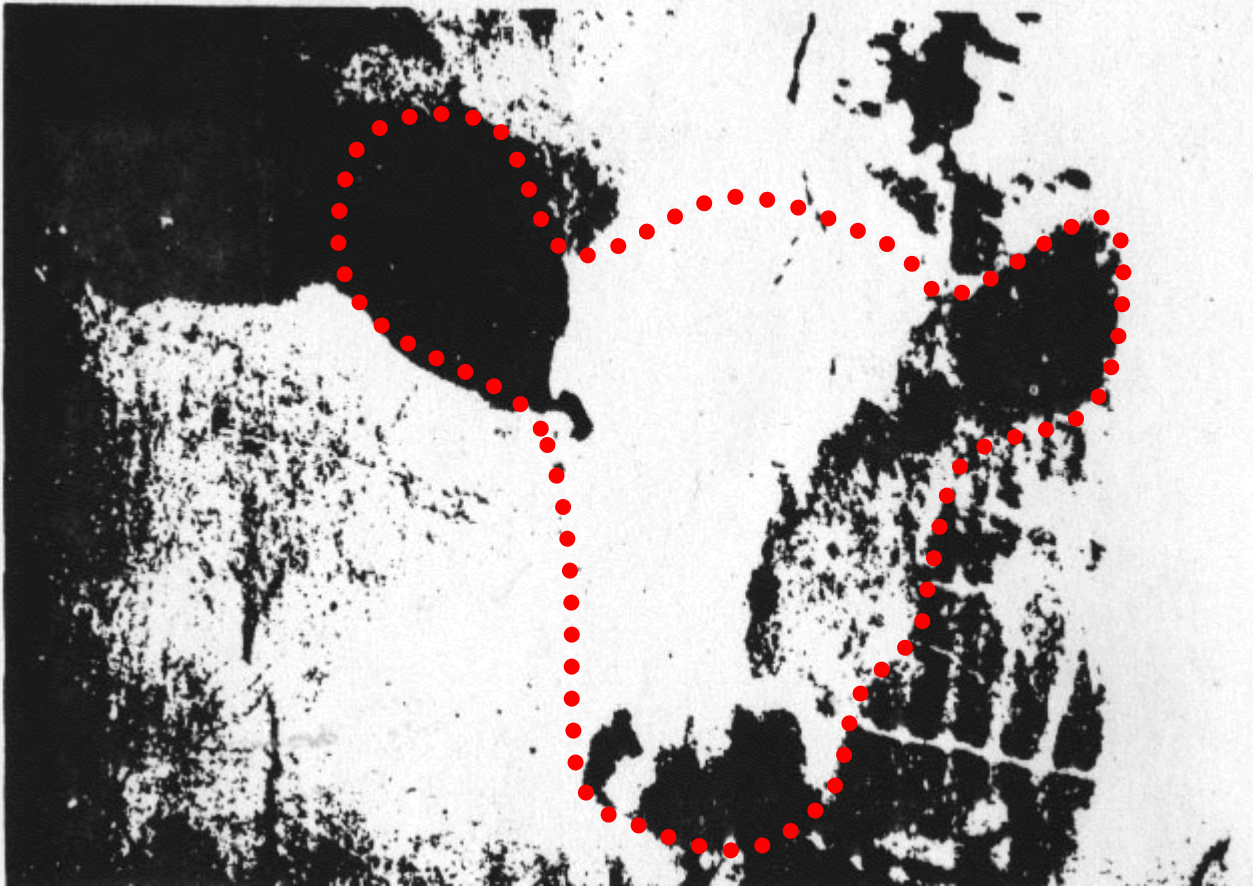
*Institute for Machine Learning, D-INFK, ETH Zurich*

# Our world, in which we live!



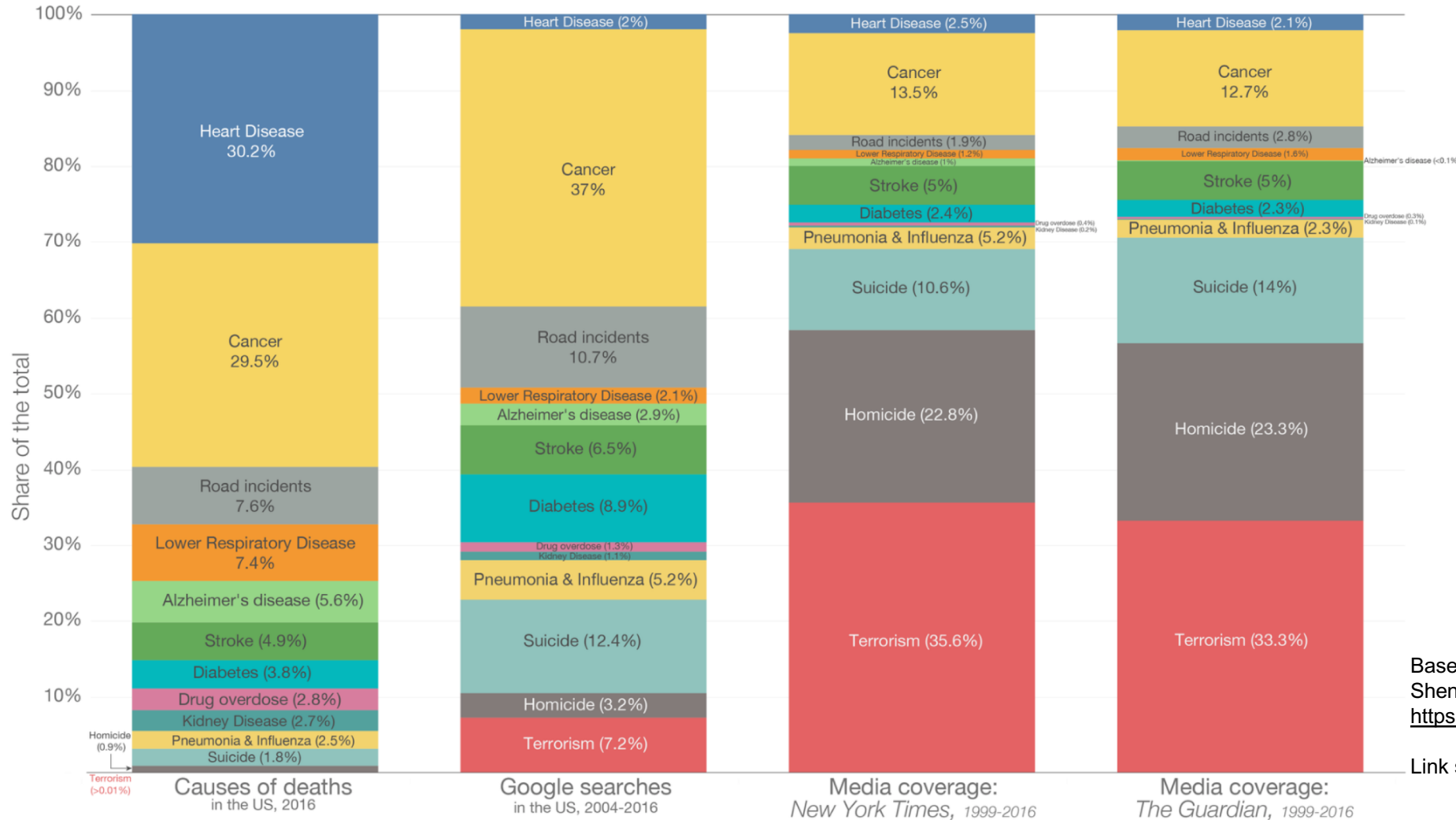


# Seeing patterns in data (vision) is difficult!



# Causes of death in the US

What Americans die from, what they search on Google, and what the media reports on



Based on data from Shen et al. (2018) – Death: reality vs. reported. <https://owenshen24.github.io/charting-death>

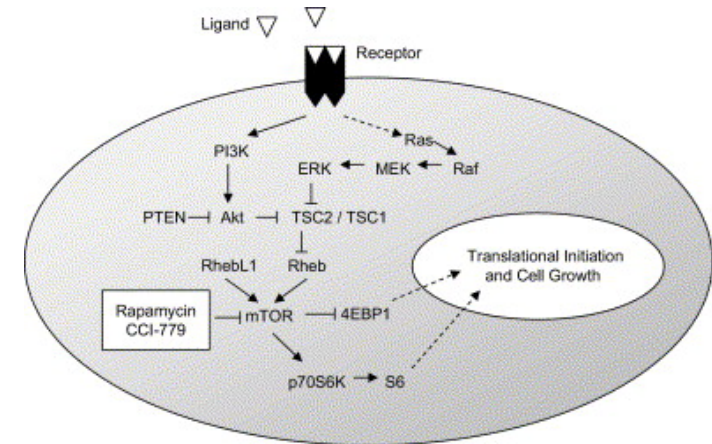
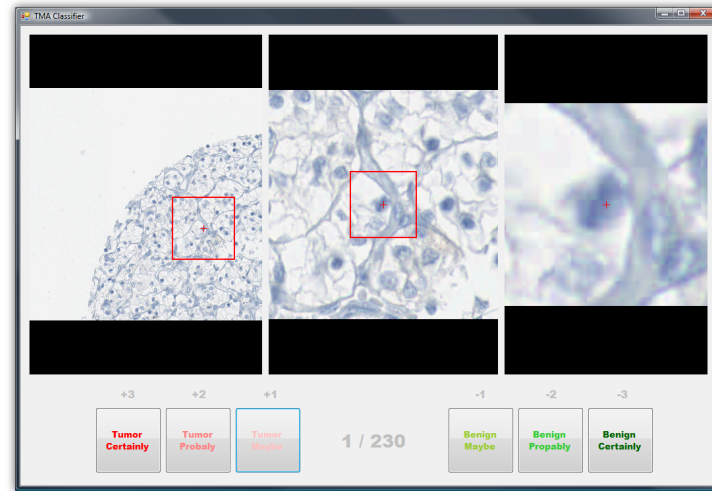
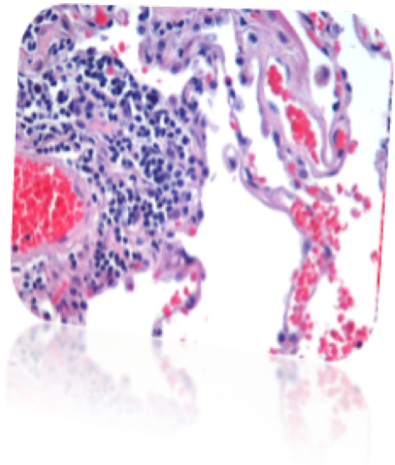
Link shared by **Alessandro Curioni**, IBM Research



# IT value generation in personalized medicine

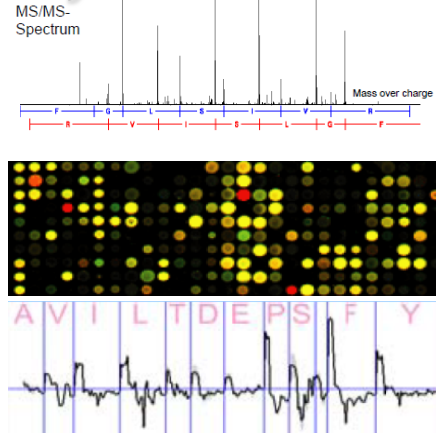


Thomas Fuchs  
MSKCC, PAIGE.AI



Activation of the mTOR Signaling Pathway in Renal Clear Cell Carcinoma. Robb et al., J Urology 177:346 (2007)

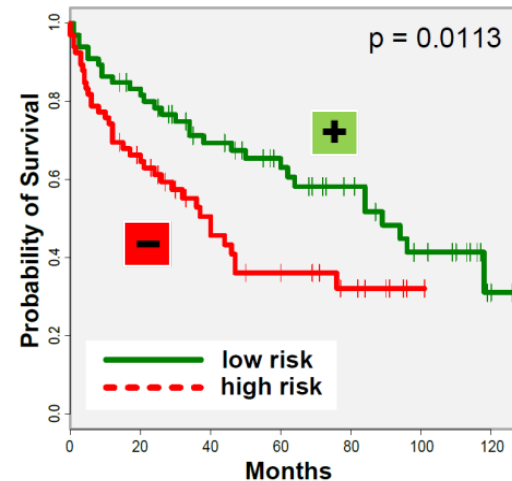
*my* Data



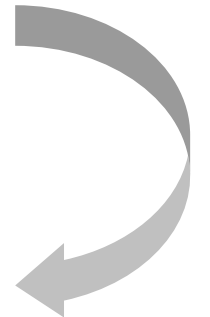
*my* Information



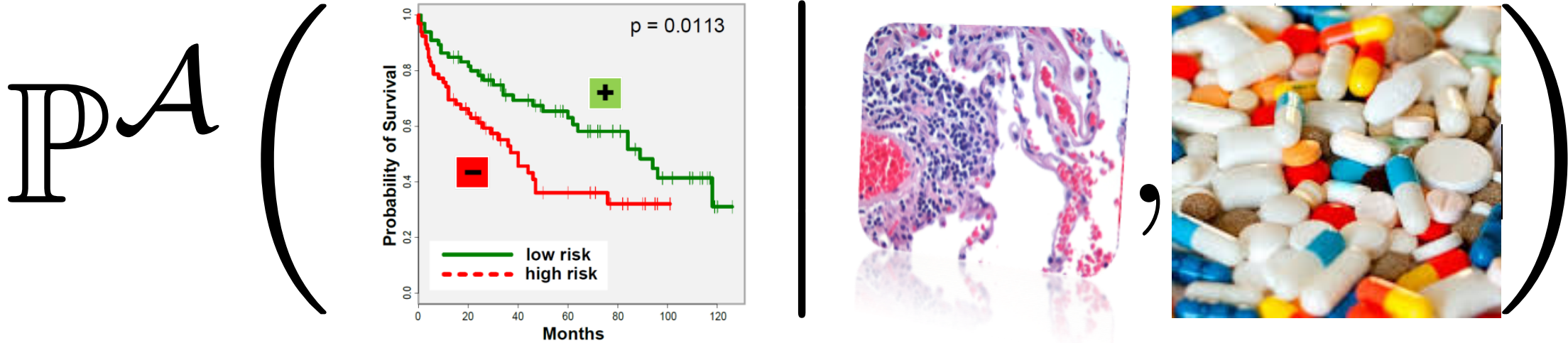
*our* Knowledge



*my* Value



# Fundamental data science questions - Which posterior distribution is encoder by algorithm $\mathcal{A}$ ?



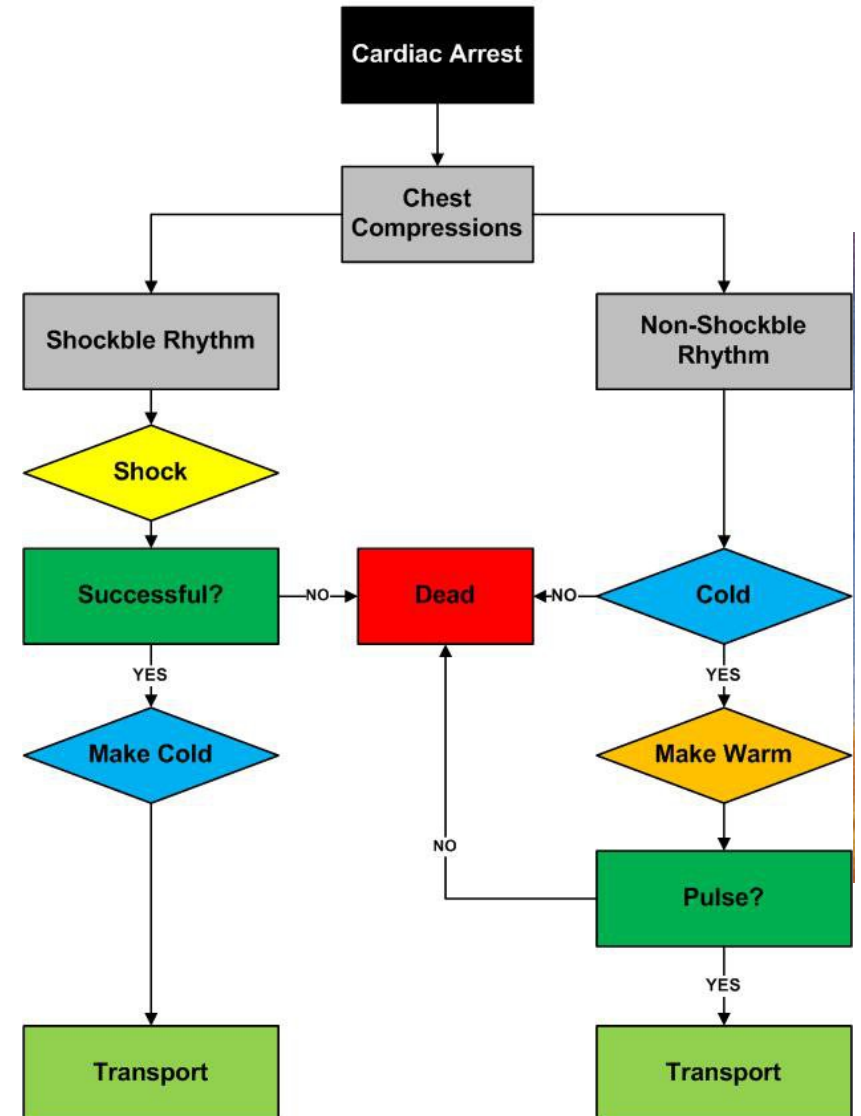


# The Algorithm: Idiom of Modern Science

(Bernard Chazelle)

- Informally, an **algorithm** is any well-defined **computational procedure**, that takes some value as **input** and produces some value as **output**. (CLRS)
- Analysis of algorithms**
  - Runtime
  - Memory consumption
  - ✗ **Robustness**
  - ✗ **Generalization**
- Learning algorithms „explore“ a complex stochastic reality!

2015 ACLS CARDIAC ARREST ALGORITHM



# Roadmap

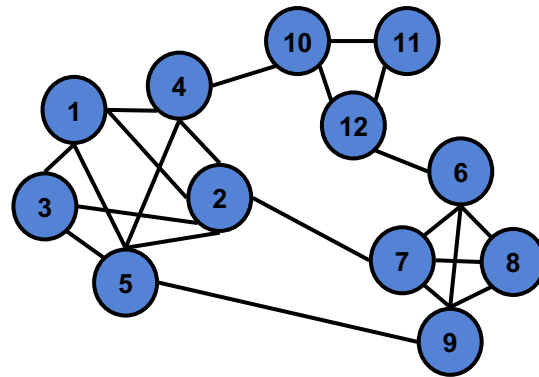
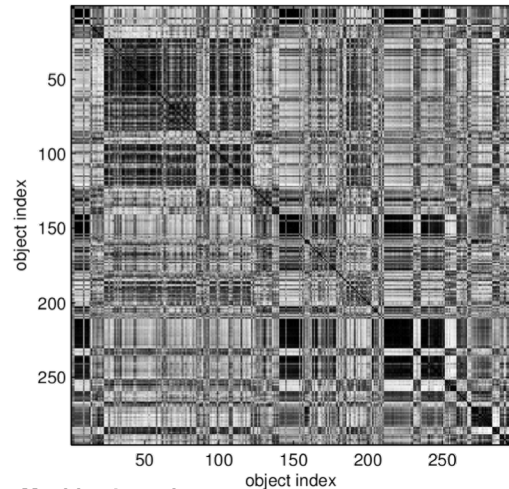
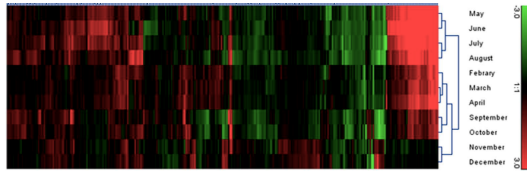
- **Algorithm design for Data Science**
  - What is the core problem? Lessons learned!
- **Algorithm validation** by information theory  
Learning optimal algorithms as open challenge!
- **Examples**
  - Cortex parcellation
  - Sparse Minimum Bisection & Community Detection Problem
- **Quo vadis – Artificial Intelligence?**



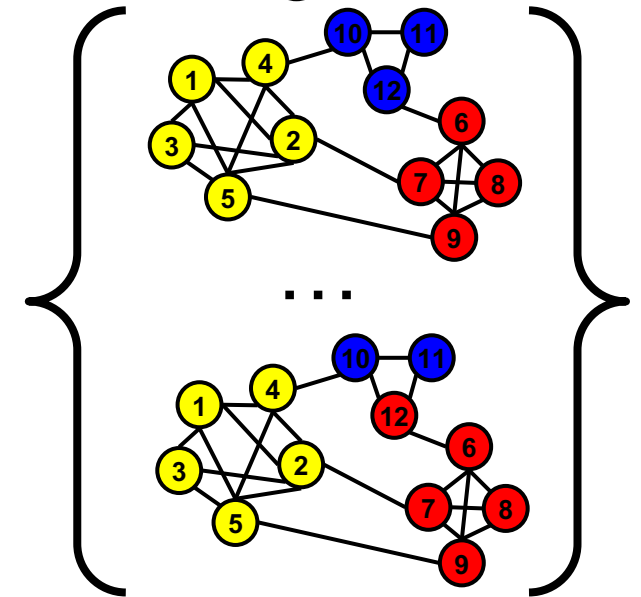
# Algorithmics for Data Science – what is the problem?

- Random inputs imply random outputs

$$\underbrace{\text{input } \mathbf{X} \sim P(\mathbf{X})}_{\text{given}} \implies \underbrace{A}_{\text{algorithm}} \implies \underbrace{\text{output } c \sim P(c|\mathbf{X})}_{\text{design}}$$



**A?**



# Core question for computer science: How can we validate (data science) algorithms?

**I. Algorithms with random variables as input compute random variables as output!**

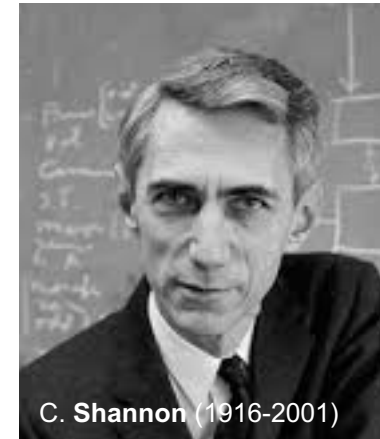
How can we prove correctness of such algorithms?

**II. Algorithms have to compute typical solutions!**

What does this mean for algorithm design?

**III. When do algorithms generalize over noise/model mismatch?**

**IV. How can algorithms autonomously improve performance?**



C. Shannon (1916-2001)



A. Kolmogorov (1903-1987)



V. Vapnik  
(1936 -)

# Typicality of solutions of random experiments

- Imagine the following **random coin flip experiment**  
 $n = 1000$  coin flips of a biased coin  $\forall i, P(\text{Head}) = P(\xi_i = 1) = p = 0.6$
- Which sequence do you want to report?**
- Minimizer of negative log-likelihood!**

$$\xi = \arg \min_{\xi_i \in \{0,1\}^n} \sum_{i=1}^n \left( -\xi_i \log p - (1 - \xi_i) \log(1 - p) \right)$$

$$= \underbrace{(1, 1, \dots, 1)}_{1000 \text{ times}}$$



# Machine Learning is not Optimization!

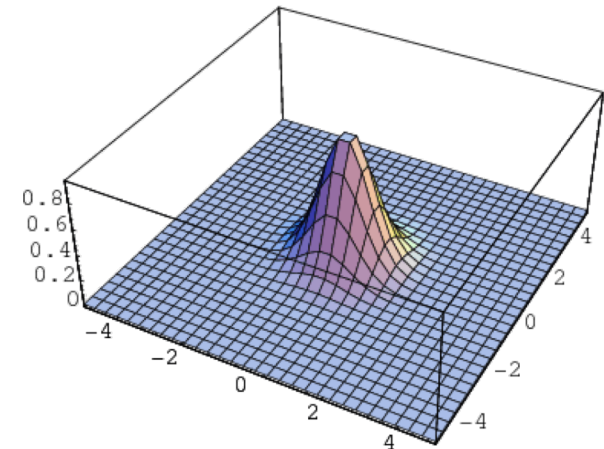
- **What you might want do, cannot be done** since we don't know  $P(\mathbf{X})$ .
- **What you can do, isn't most relevant** since it might yield atypical solutions.
- **Machine Learning algorithms localize solutions!**

We must **validate the metric** of the solution space

$$c \sim P_{\theta}(c|\mathbf{X}')$$

$$c^{\perp} \in \arg \min_{c \in \mathcal{C}} \mathbb{E}_{\mathbf{X}} R(c, \mathbf{X})$$

$$\hat{c}(\mathbf{X}') \in \arg \min_{\xi \in \mathcal{C}} R(c, \mathbf{X}')$$





# Model selection – What should we compare?

- **Standard setting:** Given are **training**, **validation** and **test** instance  $\mathbf{X}'$ ,  $\mathbf{X}''$ ,  $\mathbf{X}'''$ . We consider a set of possible models (risks)  $\{R^1, \dots, R^K : R : \mathcal{C} \times \mathcal{X} \rightarrow \mathbb{R}_+\}$ . Select the model  $R^*(., .)$  with the lowest validation error on the training solutions

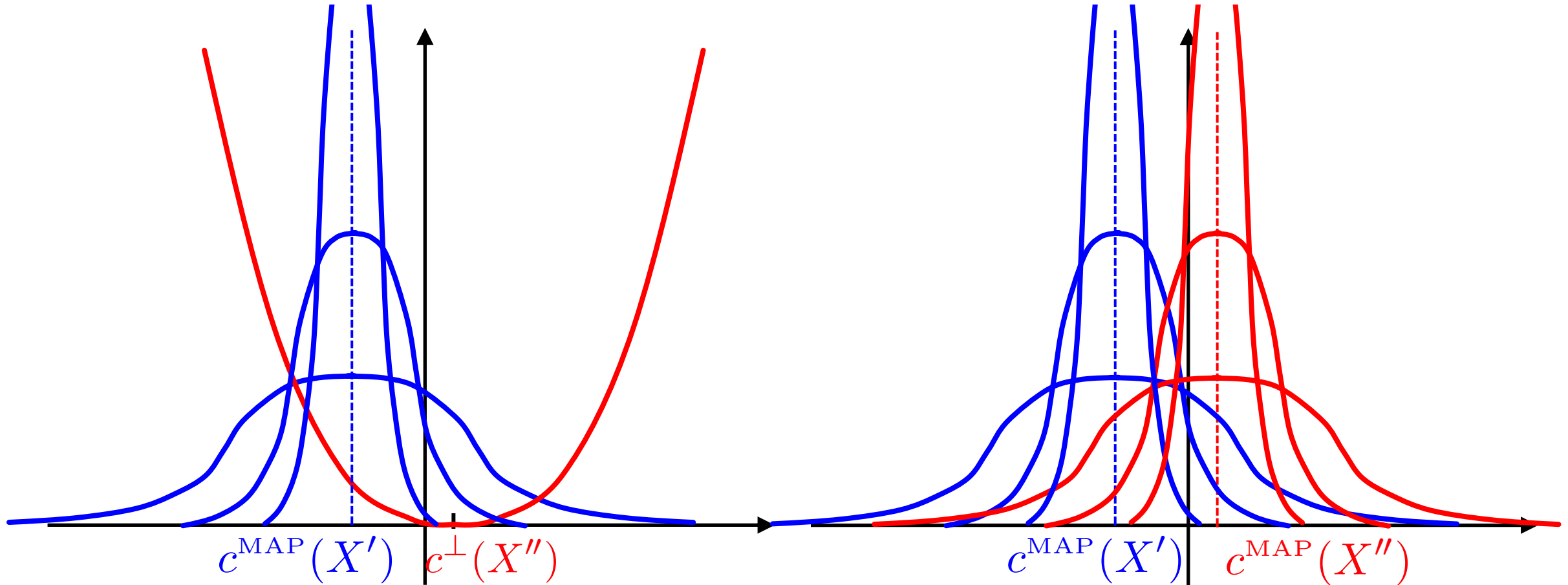
$$R^*(., .) = \arg \min_{1 \leq \alpha \leq K} \sum_{c \in \mathcal{C}} p(c | \mathbf{X}') R^\alpha(c, \mathbf{X}'')$$

- **Standard view:** „Machine Learning is stochastic optimization“ of risk:
  - Different risks with the same global minimum yield significantly different solutions under uncertainty, i.e., when the input contains noise.
- **Modeling wisdom:** Use small numbers when you encounter large uncertainties!

# Risk Minimization

versus

# Score Maximization

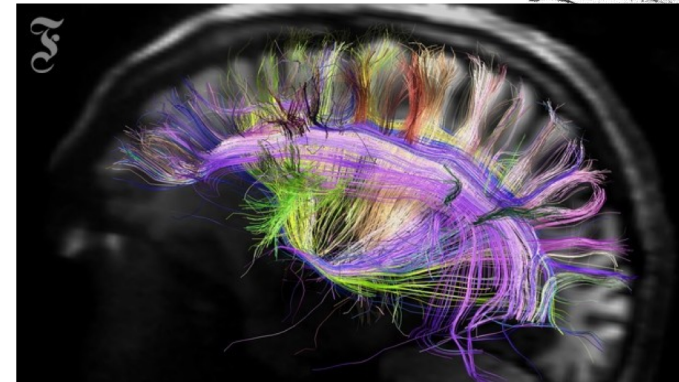
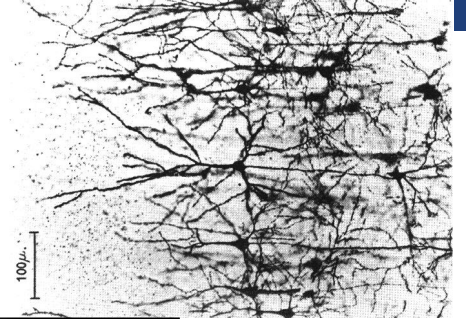


validation error =  $\sum_{c \in \mathcal{C}} P(c|X') R(c, X'')$

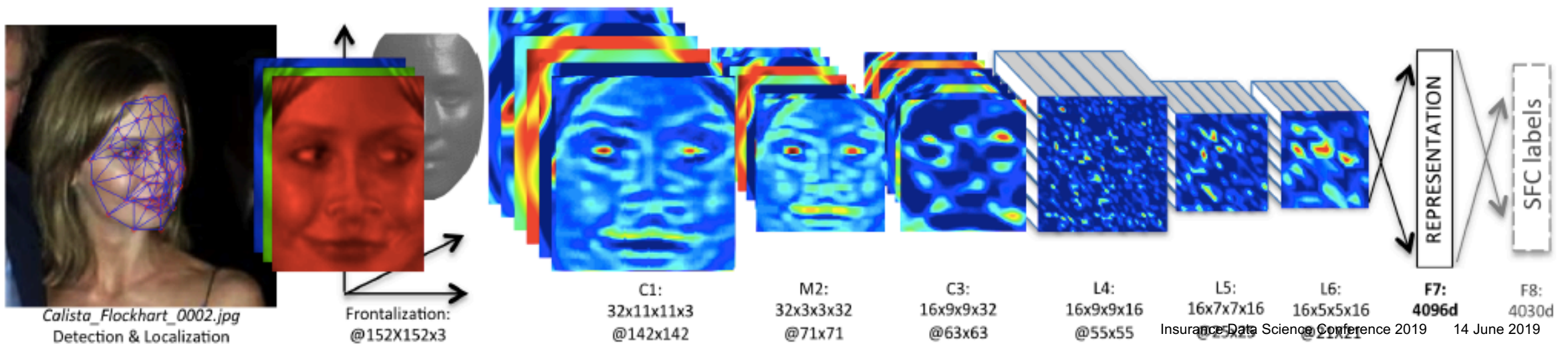
$k(X', X'') = \sum_{c \in \mathcal{C}} P(c|X') P(c|X'')$

# Learning machines master algorithmic induction and «imitate» humans

- **Biological neural networks** are adaptive and can learn.
- **Artificial neural networks** mimic these learning capabilities.
- **DeepFace** network of FaceBook



Neural networks visualized by brain scans. © VAN WEDEEN





# “Deep Network” Halluzinationen

(Courtesy of Sebastian Nowozin, 2016)



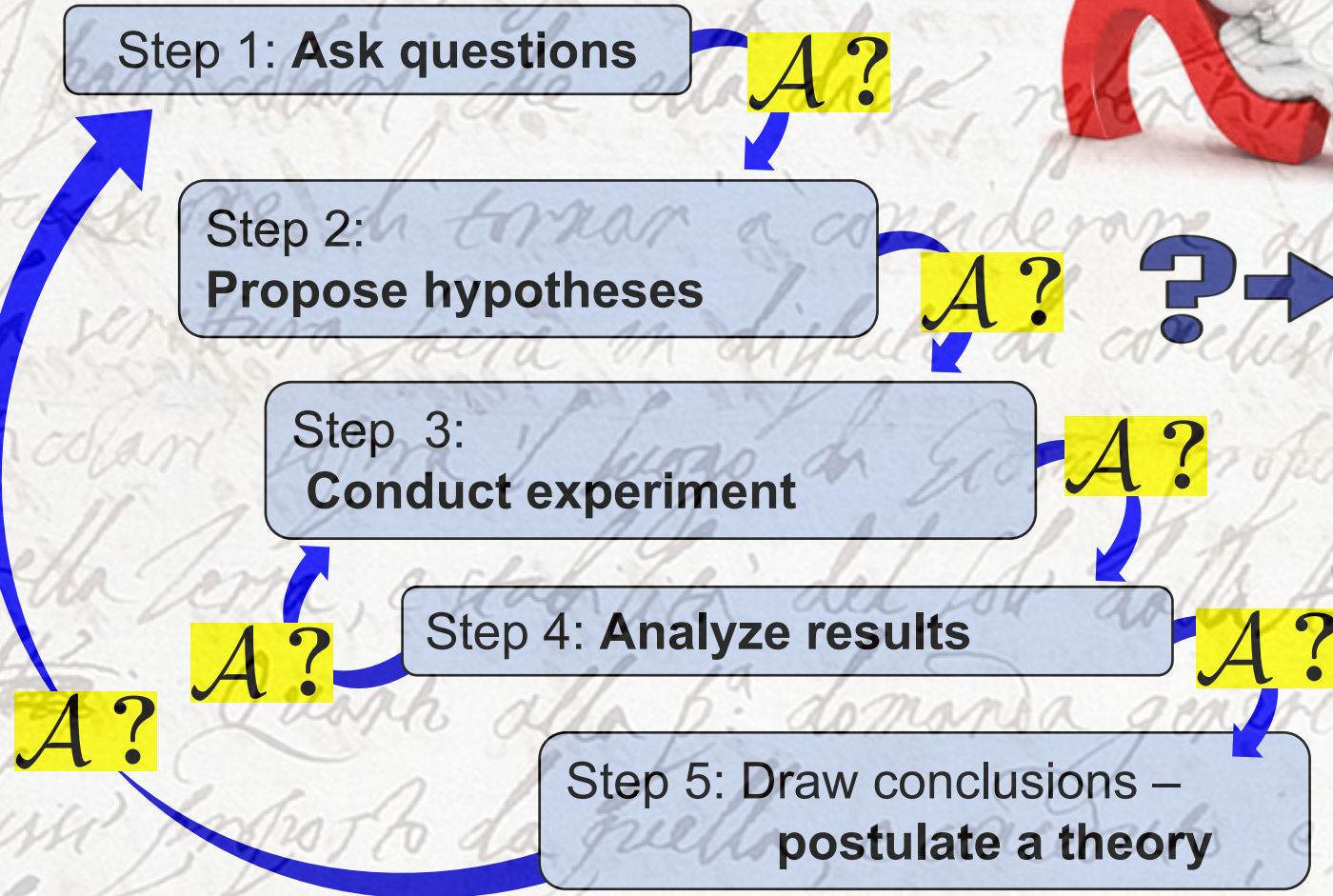
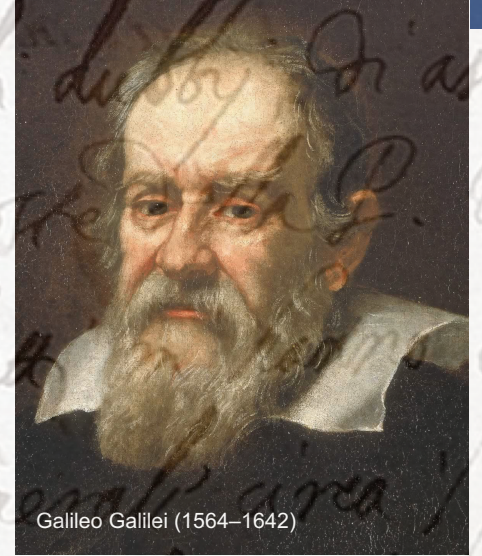


# Image interpolation with neural networks





# What is missing? The Scientific Method



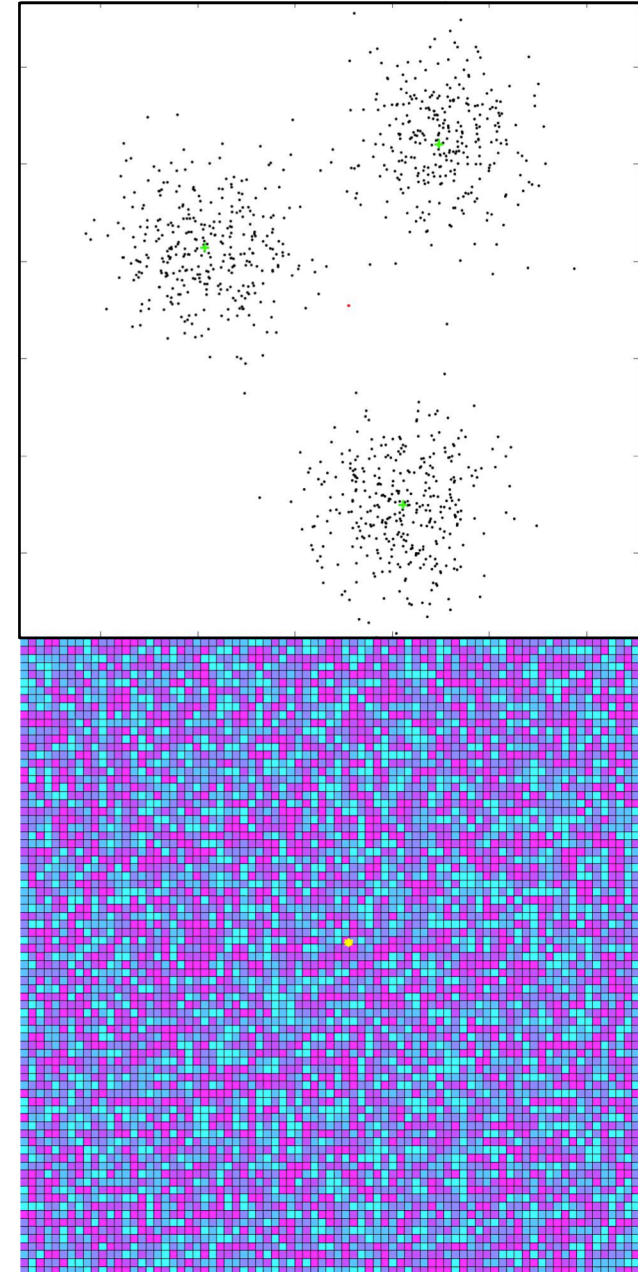


# Gibbs distributions for optimization

- Given a risk / cost function  $R : \mathcal{C} \times \mathcal{X} \rightarrow \mathbb{R}$
- Gibbs posteriors maximize entropy for expected costs  $\mathbb{E}_{c|\mathbf{X}} [R(c, \mathbf{X})]$  !

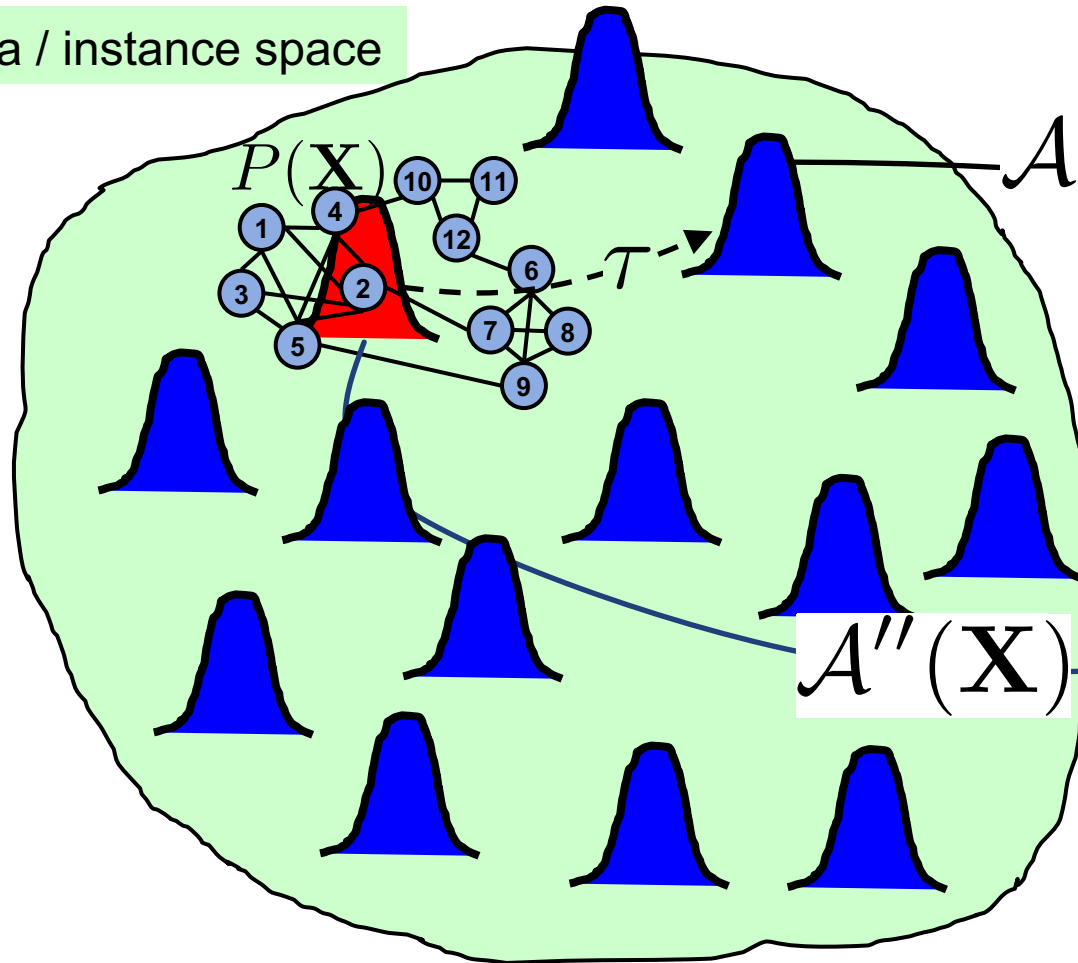
$$P_t(c|\mathbf{X}) = \frac{\exp(-\beta_t R(c, \mathbf{X}))}{\sum_{c' \in \mathcal{C}} \exp(-\beta_t R(c', \mathbf{X}))}$$

- **Robustness** by maximum entropy
- **Annealing**: increase iteratively  $\beta_t$  during algorithm execution

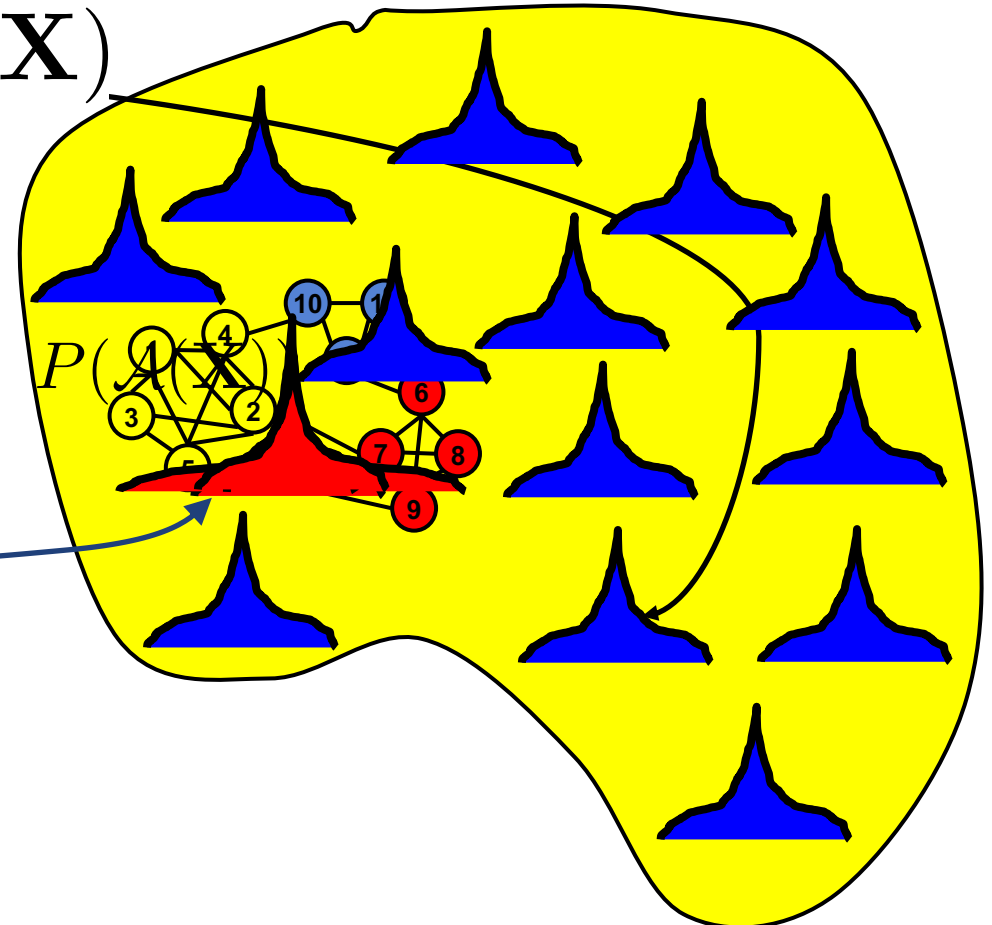


# Noisy inputs of algorithms quantize hypothesis classes

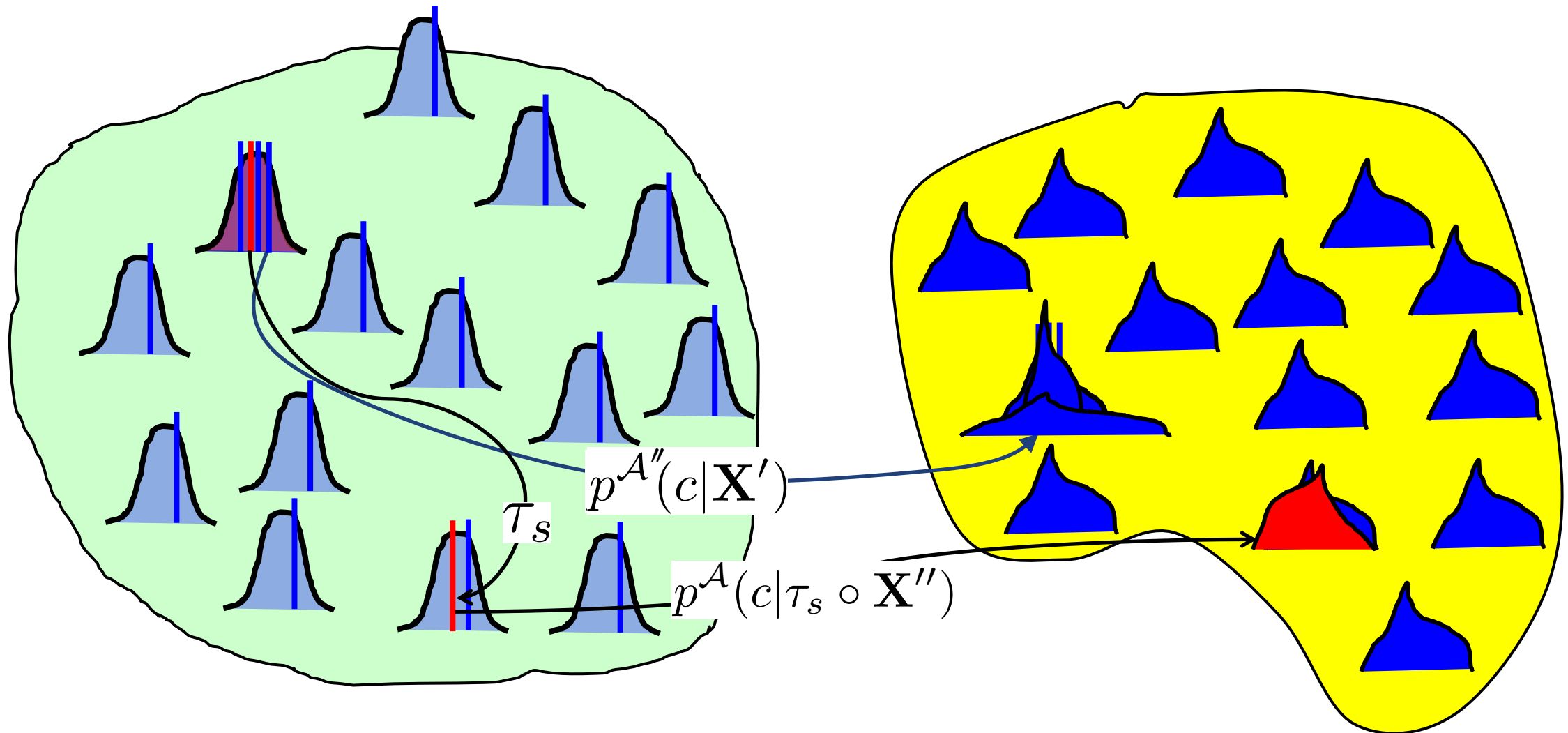
Data / instance space



Hypothesis class / solution space

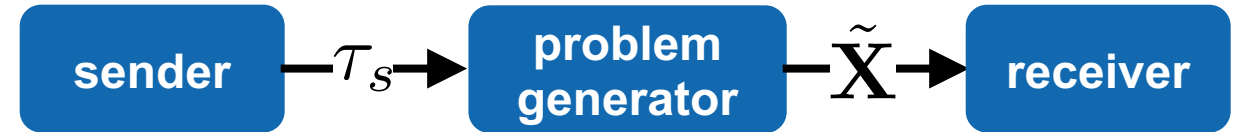


# Quantized hypothesis classes based on instances





# Communication process and decoding



- Sender sends transformation  $\tau_s$
- Receiver accepts instance  $\tilde{\mathbf{X}} := \tau_s \circ \mathbf{X}''$  with  $\mathbf{X}', \mathbf{X}'' \sim P(\mathbf{X})$  and decodes the transformation by **maximizing expected posterior**

$$\hat{\tau} \in \arg \max_{\tau \in \mathcal{T}} \mathbb{E}_{c|\tau \circ \mathbf{X}'} (c|\tau_s \circ \mathbf{X}'')$$

- **Error** events are decisions with  $\hat{\tau} \neq \tau_s$
- => Calculate probability**  $P(\hat{\tau} \neq \tau_s | \tau_s)$

## Error probability $P(\hat{\tau} \neq \tau_s | \tau_s)$

- Estimate error given random transformations  $\tau \in \mathcal{T}$  and test data  $\tilde{\mathbf{X}} := \tau_s \circ \mathbf{X}''$

$$k^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'') := \sum_{c \in \mathcal{C}(\mathbf{X}'')} p^{\mathcal{A}}(c | \mathbf{X}') p^{\mathcal{A}}(c | \mathbf{X}'')$$

$$\begin{aligned} \mathbb{P}(\hat{\tau} \neq \tau_s | \tau_s) &= \mathbb{P}\left(\max_{j \neq s} \mathbb{E}_{c | \tau_j \circ \mathbf{X}'} p^{\mathcal{A}}(c | \tilde{\mathbf{X}}) > \mathbb{E}_{c | \tau_s \circ \mathbf{X}'} p^{\mathcal{A}}(c | \tilde{\mathbf{X}}) | \tau_s\right) \\ &\leq \sum_{j \neq s} \mathbb{P}\left(\mathbb{E}_{c | \tau_j \circ \mathbf{X}'} p^{\mathcal{A}}(c | \tilde{\mathbf{X}}) > k^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'') | \tau_s\right) \\ &\leq M \mathbb{P}\left(\mathbb{E}_{c | \tau_{\neq s} \circ \mathbf{X}'} p^{\mathcal{A}}(c | \tilde{\mathbf{X}}) > k^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'') | \tau_s\right) \\ &\leq M \mathbb{E}_{\mathbf{X}', \mathbf{X}''} \frac{\mathbb{E}_{\tau_{\neq s}} \mathbb{E}_{c | \tau_{\neq s} \circ \mathbf{X}'} p^{\mathcal{A}}(c | \tilde{\mathbf{X}})}{k^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'')} \end{aligned}$$

# Generalization capacity from typicality

**Theorem:** Asymptotic error free ( $\lim_{n \rightarrow \infty} P(\hat{\tau} \neq \tau_s | \tau_s) = 0$ ) *identification of hypotheses* is achievable if

$$P(\hat{\tau} \neq \tau_s | \tau_s) \leq \exp\left(-(\mathcal{I} - \log M)\right) \rightarrow 0 \quad \text{with}$$

$$\mathcal{I} = \mathbb{E}_{\mathbf{X}', \mathbf{X}''} \log\left(|\mathcal{C}| k^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'')\right)$$

$$k^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'') = \sum_{c \in \mathcal{C}} p^{\mathcal{A}}(c | \mathbf{X}') p^{\mathcal{A}}(c | \mathbf{X}'') \in [0, 1]$$

# Learning algorithms localize typical solutions

- **“Posteriors”** for probable data  $\mathbf{X}'$ ,  $\mathbf{X}''$  should agree!

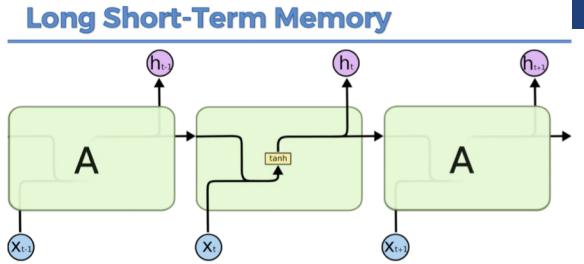
$$k^A(\mathbf{X}', \mathbf{X}'') = \sum_{c \in \mathcal{C}} p^A(c|\mathbf{X}') p^A(c|\mathbf{X}'') \in [0, 1]$$

A too broad or too narrow posterior  $p^A(\cdot|\mathbf{X})$  yields a small kernel value  $k^A(\mathbf{X}', \mathbf{X}'')$ ! Optimize width of  $p^A(\cdot|\mathbf{X})$ .

- **Optimal posterior**

$$P^* \in \arg \max_t \mathbb{E}_{\mathbf{X}', \mathbf{X}''} \log(|\mathcal{C}| k_t^A(\mathbf{X}', \mathbf{X}''))$$

# Learning an algorithm: open challenge!



- **Given a set of algorithms**  $\left\{ \mathcal{A}^{(\alpha)}(\mathbf{X}) = \langle P_0^{(\alpha)}(c|\mathbf{X}), \dots, P_{t^*}^{(\alpha)}(c|\mathbf{X}) \rangle \right\}$
- **Select posterior**  $\mathcal{A}^{(\alpha)}(\mathbf{X})$  s.t. generalization capacity is maximized

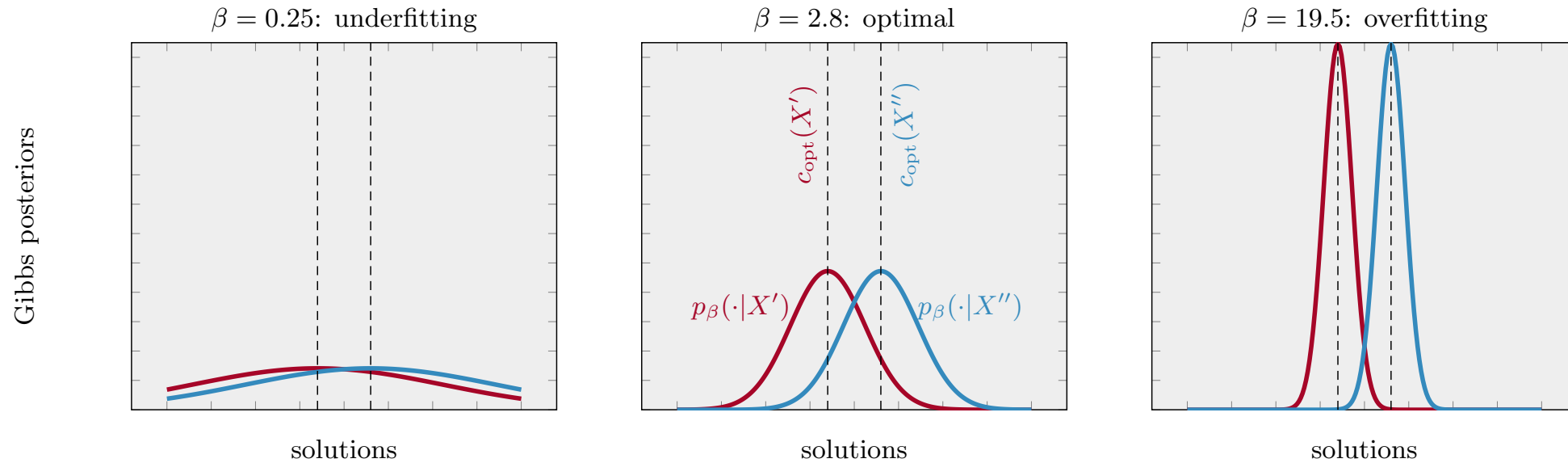
$$P^* \in \arg \max_{\{\mathcal{A}\}} \max_t \mathbb{E}_{\mathbf{X}', \mathbf{X}''} \log(|\mathcal{C}| k_t^{\mathcal{A}}(\mathbf{X}', \mathbf{X}''))$$

- **Problem:** We cannot evaluate  $\mathbb{E}_{\mathbf{X}', \mathbf{X}''} \log \dots$  since  $P(\mathbf{X}', \mathbf{X}'')$  is unknown!
- **Statistical Learning Theory:** bound expectation by sample average

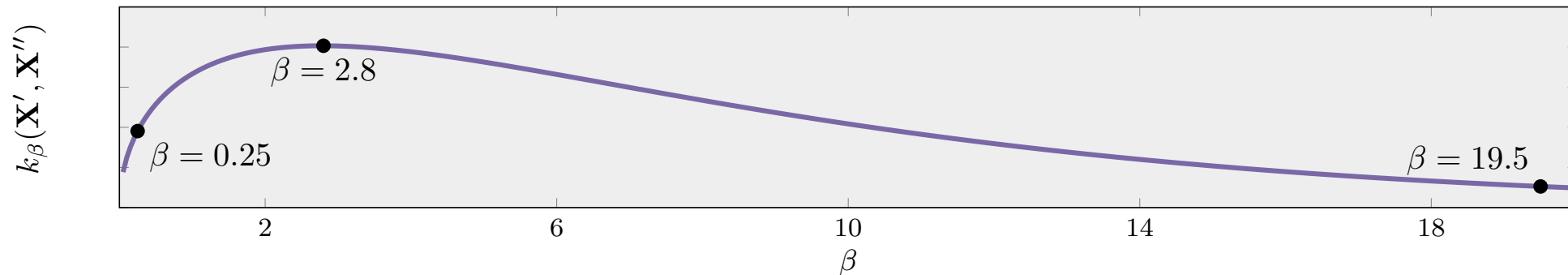
$$\mathbb{E}_{\mathbf{X}', \mathbf{X}''} \log(|\mathcal{C}| k_t^{\mathcal{A}}(\mathbf{X}', \mathbf{X}'')) \geq \frac{1}{L} \sum_{l \leq L} \log(|\mathcal{C}| k_t^{\mathcal{A}}(\mathbf{X}'_l, \mathbf{X}''_l)) - \text{penalty}$$



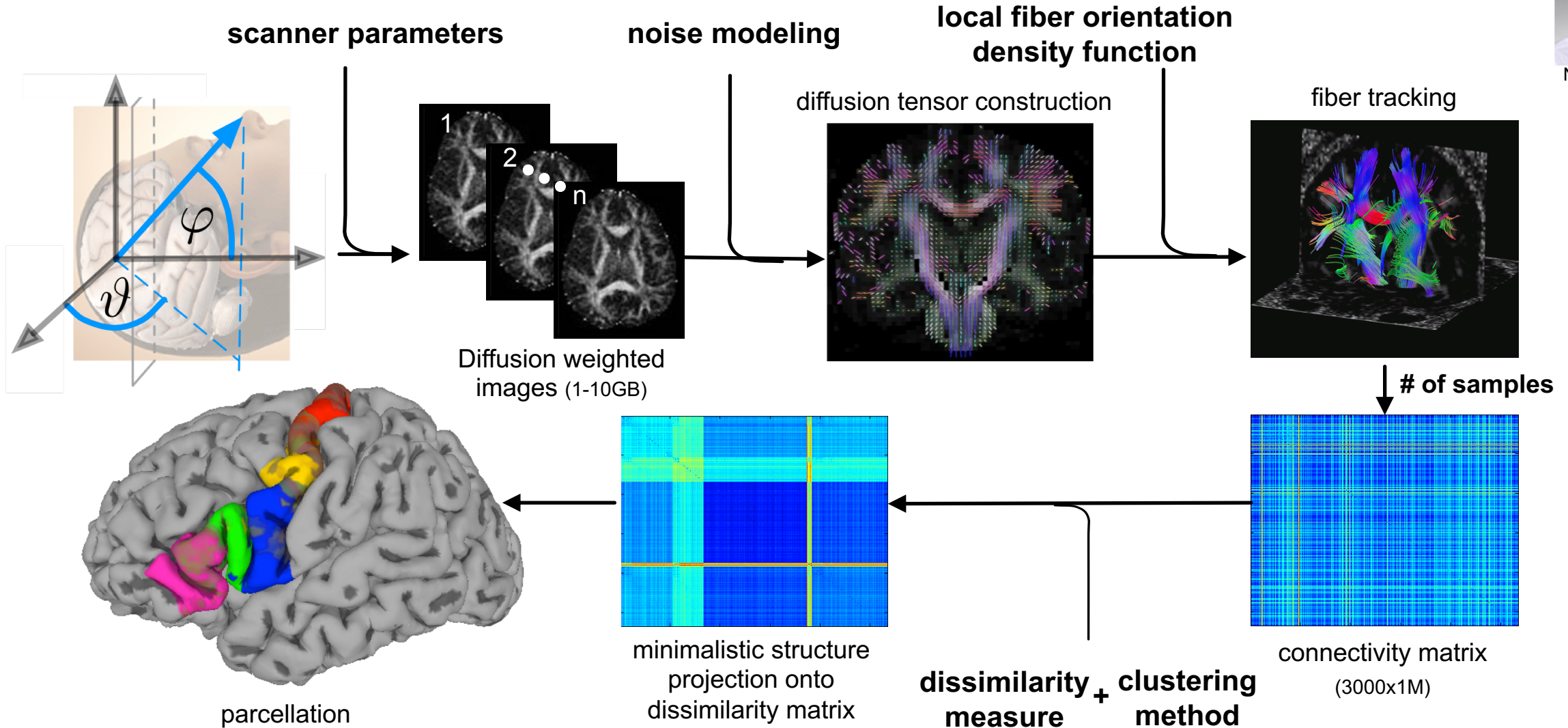
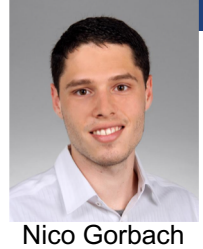
# Maximal score at finite $\beta$



(a)



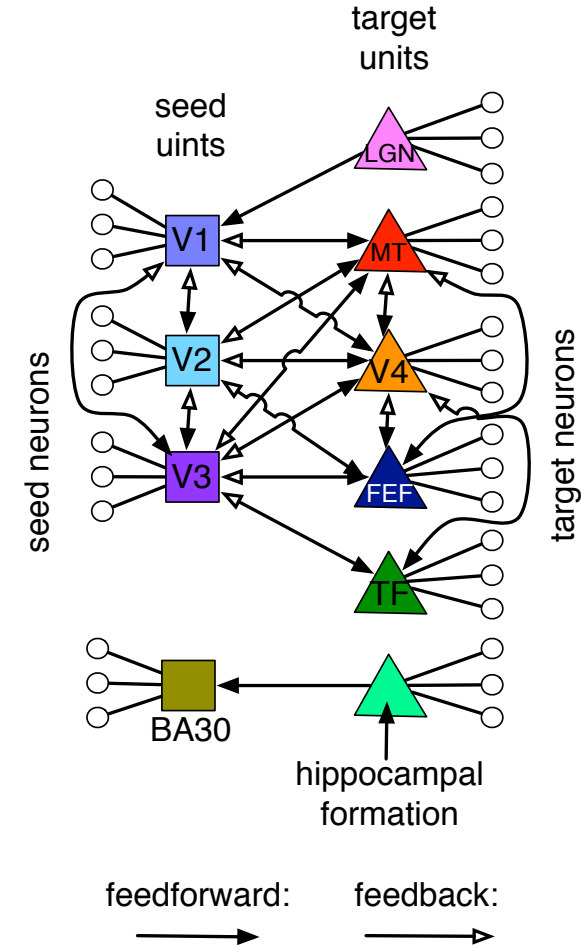
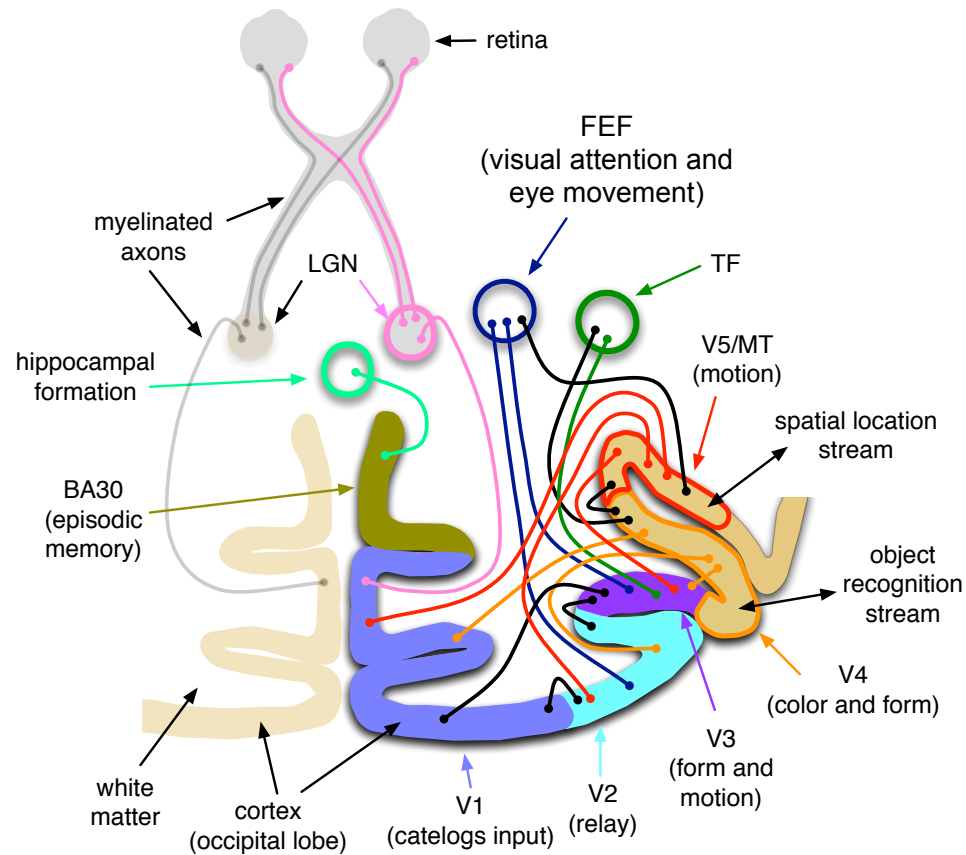
# Cortex Parcellation with diffusion weighted tensor imaging



# Systems Neuroscience

Subset of the visual system in the macaque monkey.

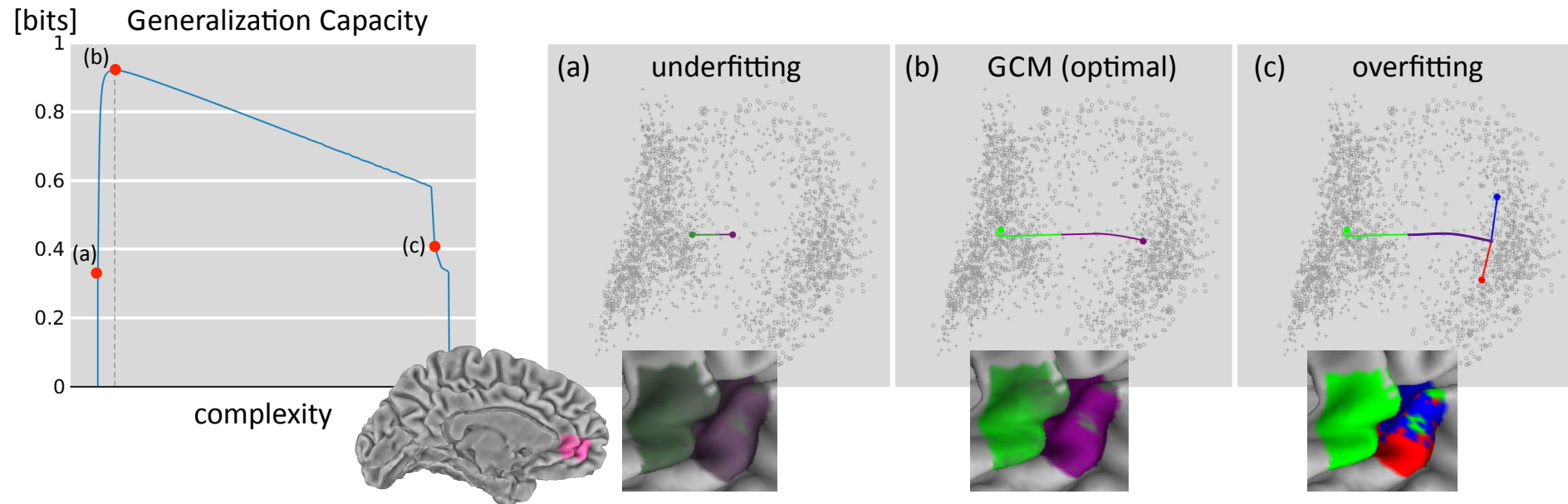
Target connections are limited for illustration purposes.



- The brain is considered as an ensemble of functionally specialized units coupled together in a modulatory fashion (Friston, 2002).

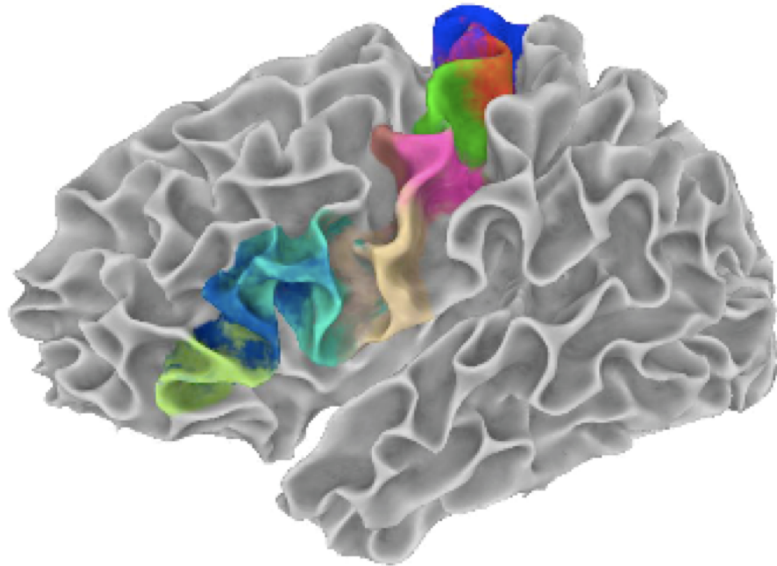
# Under- and overfitting in parcellation

- Connectivity of two brain regions is analyzed
- Generalization capacity maximizer (GCM) outperforms empirical risk minimizer

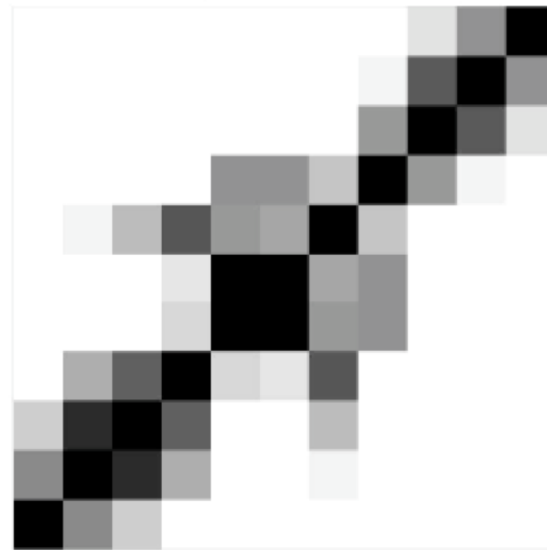


# Dynamics of cortex parcellation

- Start at low resolution
- Estimate parcellations with higher resolution
- Stop at maximal generalization capacity

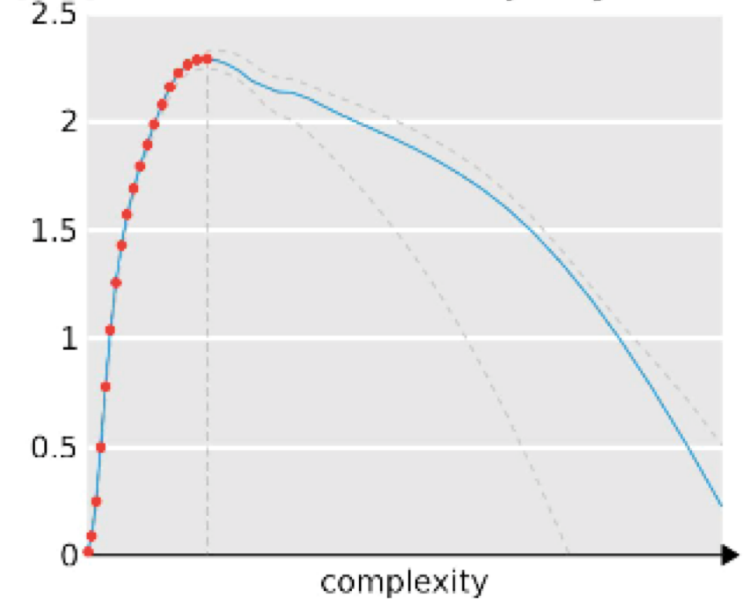


Dissimilarity between Centroids



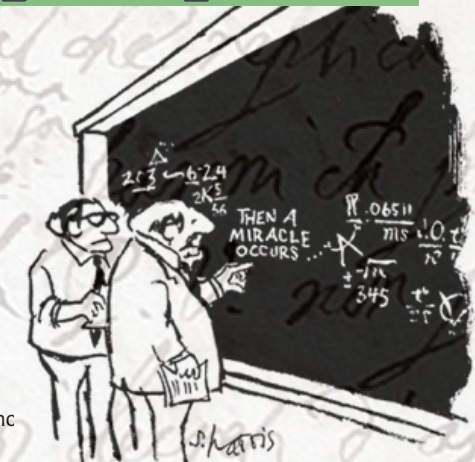
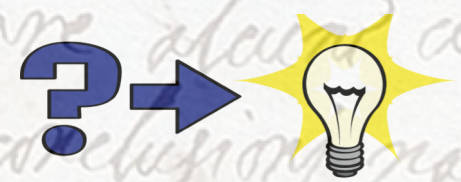
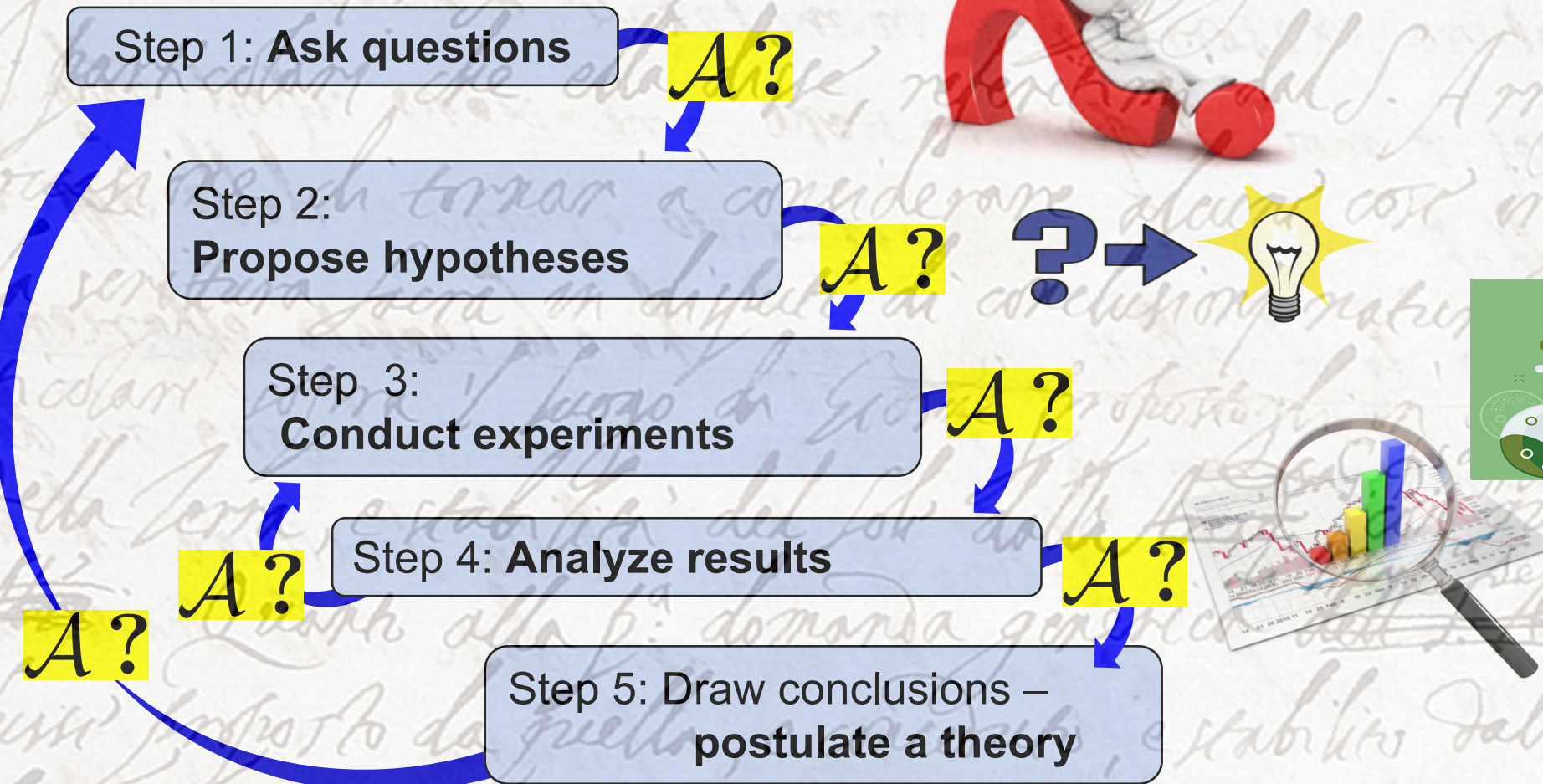
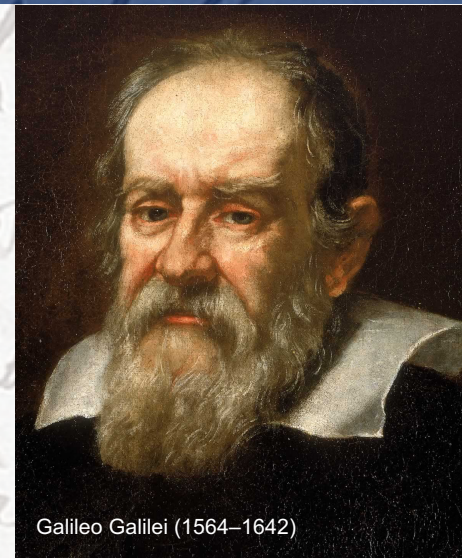
[bits]

Generalization Capacity





# What is missing? The scientific method



# Roadmap

- **Algorithm design for Data Science**
  - What is the core problem? Lessons learned!
- **Algorithm validation** by information theory  
Learning optimal algorithms as open challenge!
- **Examples**
  - Cortex parcellation
  - Sparse Minimum Bisection & Community Detection Problem
- **Quo vadis – Artificial Intelligence?**



# Outlook and Lessons learned

1. Algorithms are models of posteriors and localize in solution spaces.
  2. Learning requires validation of algorithms, not “only” verification.
  3. Conditioned on inputs, **algorithms** are characterized by a **generalization capacity, i.e., an optimal resolution of the hypothesis class!**
- ⇒ **structure specific information** in data.
- ⇒ Relate *statistical* complexity to *computational* complexity!

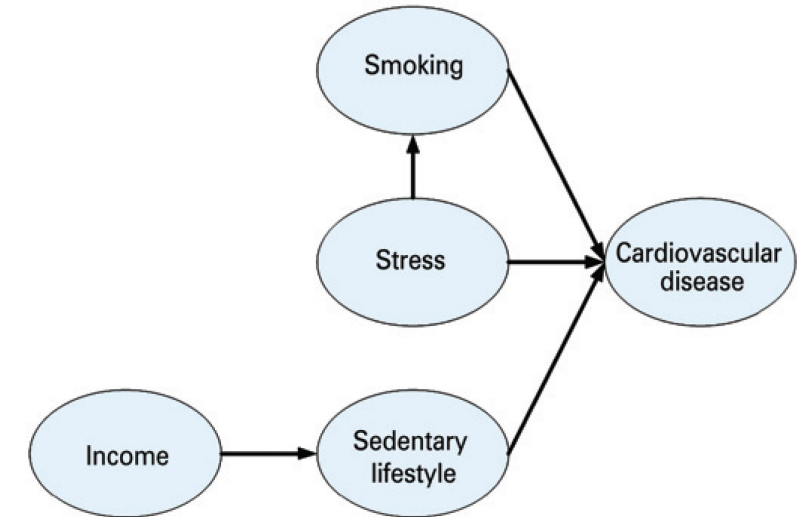


# Expert systems enable Artificial Intelligence !?

(Strategy of AI researchers in 60<sup>th</sup> to 80<sup>th</sup>)

## Intelligent behavior as a programming problem

- + Inference by rule systems and logic calculus
- Problem: *Knowledge Engineering* via experts



- **Experts invent symbols**
- **Learning algorithms discover relations, i.e. conditional probabilities**