

Bayesian Poisson log-bilinear models for mortality projections with multiple populations

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joint work with Katrien Antonio and Wilbert Ouburg

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Outline

State of the art

Multi–population models

Bayesian framework

R implementation

Results

State of the art: age–period mortality tables

- ▶ In a dynamic context, mortality is assumed to be a function of both **age x** and **calendar year t** .
- ▶ $q_{x,t}$: the probability of dying at age x , for an individual aged x in year t .
- ▶ $\mu_{x,t}$: the force of mortality, which is the instantaneous rate of dying, for an individual aged x in year t .
- ▶ The relation between the two quantities is $q_{x,t} \approx 1 - \exp\{-\mu_{x,t}\}$.
- ▶ **Forecasting**: simulate $q_{x,t}$ beyond $t = T$, use these in e.g. **annuity calculations**.

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Bayesian Poisson **log-bilinear models** for mortality projections with multiple populations.

State of the art: LC type models

- ▶ Lee & Carter (LC) (1992, JASA)

$$\log \mu_{x,t} = \alpha_x + \beta_x \cdot \kappa_t$$

State of the art: LC type models

- ▶ Lee & Carter (LC) (1992, JASA)

$$\log \mu_{x,t} = \alpha_x + \beta_x \cdot \kappa_t$$

- ▶ Renshaw and Haberman (2003, IME) model:

$$\log \mu_{x,t} = \alpha_x + \beta_{x,1} \cdot \kappa_{t,1} + \beta_{x,2} \cdot \kappa_{t,2}$$

- Avoids the trivial correlation structure of the original LC model.
- Captures age and time dynamics in a more flexible way.
- Constraints: for $j = 1, 2$

$$\sum_x \beta_{x,j} = 1, \quad \sum_t \kappa_{t,j} = 0 \quad \text{and} \quad \sum_t \kappa_{t,1} \cdot \kappa_{t,2} = 0.$$

- Orthogonality constraint ← not always trivial.

Bayesian **Poisson** log-bilinear
models for mortality projections
with multiple populations.

State of the art: likelihood assumption

▶ We introduce the following (random) variables:

- $D_{x,t}$: the number of deaths at age x in year t ;
- $E_{x,t}$: the exposure-at-risk at age x in year t .

▶ Likelihood assumption:

$$D_{x,t} | E_{x,t} \cdot \mu_{x,t} \sim \text{Poisson}(E_{x,t} \cdot \mu_{x,t}).$$

▶ Motivation for Poisson assumption:

- stems from survival likelihood (see [Pitacco et al., 2009](#)),
- account appropriately for uncertainty in number of deaths.

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Why multi–population mortality models?

- ▶ Use **larger** data set **at full**.
- ▶ To **account for group membership** of populations and countries (e.g. Western Europe).
- ▶ More **robust modeling** by using a larger data set.
- ▶ To obtain **consistent/coherent** projections (e.g. Dutch males and females projections can not diverge).
- ▶ To handle **basis risk**.
- ▶ **Increasing attention** for this setting, see e.g. recent projection by Royal Dutch Actuarial Association (AG-AI) and by the Institute of Actuaries in Belgium (see Antonio, Devolder & Devriendt, 2015).

Multi-population mortality models

Our paper puts focus on:

- ▶ **LC-2,t** model,

$$\log \mu_{x,t}^{(i)} = \underbrace{\alpha_x^{(i)}}_{i\text{-specific}} + \underbrace{\beta_{x,1}^{(i)}}_{i\text{-specific}} \cdot \underbrace{K_t}_{\text{Common}} + \underbrace{\beta_{x,2}^{(i)} \cdot \kappa_t^{(i)}}_{i\text{-specific}}$$

- ▶ **Li & Lee (LL)** model (see Li & Lee, 2005, Demography),

$$\log \mu_{x,t}^{(i)} = \underbrace{\alpha_x^{(i)}}_{i\text{-specific}} + \underbrace{B_x \cdot K_t}_{\text{Common}} + \underbrace{\beta_{x,2}^{(i)} \cdot \kappa_t^{(i)}}_{i\text{-specific}}$$

Comparison

▶ LC-2,t model:

- Able to apply **orthog. constraint**,
- Link populations through a **time** parameter (K_t),
- **NOT coherent** (due to $\beta_{x,1}^{(i)}$),
- Studied by Danesi et al. (2015).

▶ LL model:

- **NOT** able to apply **orthog. constraint** (two step approach),
- Link populations through **age** and **time** parameter (B_x, K_t),
- **Coherent** (due to B_x),
- Studied by Li & Lee (2005) and Li (2013).

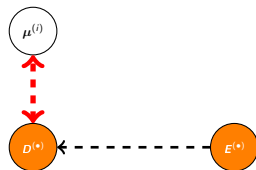
Bayesian Poisson log-bilinear models for mortality projections with multiple populations.

Why the Bayesian framework?

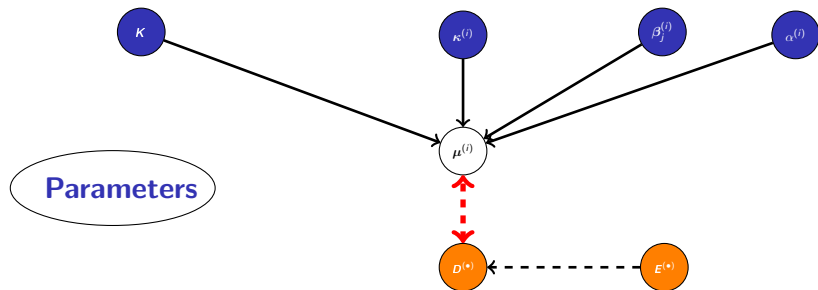
Within the Bayesian framework we are able to:

- ▶ Unify calibration step + forecast step
consistent period effects.
- ▶ Incorporate parameter uncertainty
account for all sources of uncertainty in forecasts.
- ▶ Handle small populations and missing data (e.g. portfolio data or data on regions of a country).

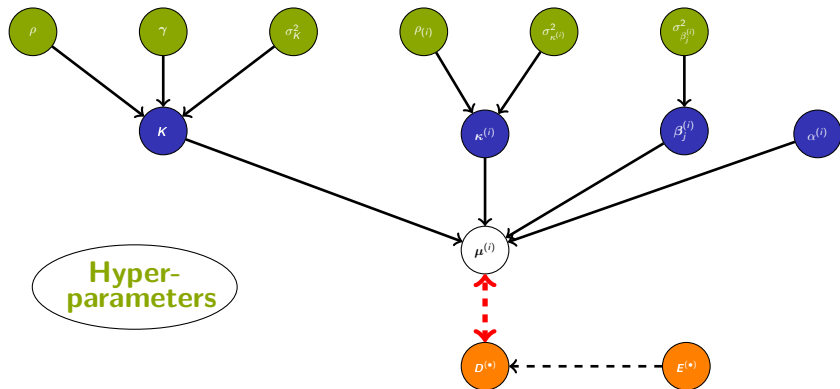
Bayesian framework: LC-2,t (DAG)



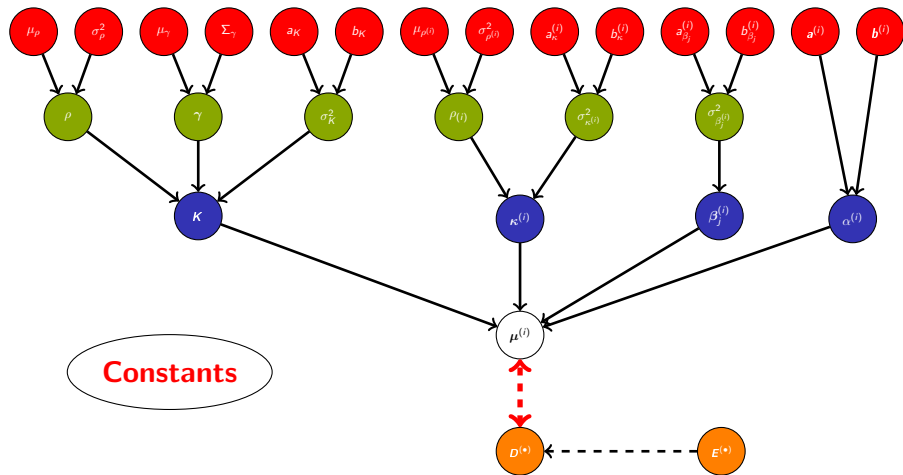
Bayesian framework: LC-2,t (DAG)



Bayesian framework: LC-2,t (DAG)



Bayesian framework: LC-2,t (DAG)



Bayesian framework: time series prior

- ▶ For the K_t we assume **AR(1)** with **linear trend**

$$K_t = \eta_t + \rho(K_{t-1} - \eta_{t-1}) + \epsilon_t \text{ with } \epsilon_t \sim \mathcal{N}(0, \sigma_K^2),$$

where $\eta_t := \gamma_1 + \gamma_2 t$.

- ▶ Thus, prior for K_t

$$K_t | K_1, \dots, K_{t-1} \sim \mathcal{N}(\eta_t + \rho(K_{t-1} - \eta_{t-1}), \sigma_K^2) \quad (1)$$

$$K_1 \sim \mathcal{N}\left(\eta_1, \frac{\sigma_K^2}{1 - \rho^2}\right). \quad (2)$$

- ▶ A Gaussian Markov Random Field (GMRF) (see Rue et al. (2005))

$$\pi(\mathbf{K}) \sim \mathcal{N}_T(\mathbf{V}\boldsymbol{\gamma}, \sigma_K^2 \mathbf{Q}^{-1}) \quad (3)$$

- ▶ Similar for all $\kappa_t^{(i)}$ but **without** a linear trend (see Li & Lee (2005)).

Bayesian framework: time series prior

► Hereby,

$$\boldsymbol{\gamma} = (\gamma_1, \gamma_2),$$

$$\mathbf{Q} = \mathbf{Q}_{T,T} = \begin{pmatrix} 1 & -\rho & 0 & \dots & 0 \\ -\rho & 1 + \rho^2 & -\rho & \dots & 0 \\ 0 & -\rho & \ddots & \ddots & 0 \\ \vdots & \vdots & \ddots & 1 + \rho^2 & -\rho \\ 0 & 0 & \dots & -\rho & 1 \end{pmatrix}, |\mathbf{Q}| = 1 - \rho^2,$$

$$\mathbf{V}' = \begin{pmatrix} 1 & 2 & \dots & T \\ 1 & 1 & \dots & 1 \end{pmatrix},$$

where T is the total number of the years.

Bayesian framework: priors for the age specific parameters

- ▶ For the **age specific** parameters $\beta_{x,j}^{(i)}$ and B_x ,

$$\beta_{x,j}^{(i)} \sim \mathcal{N}\left(\frac{1}{M}, \sigma_{\beta_j^{(i)}}^2\right) \text{ and } B_x \sim \mathcal{N}\left(\frac{1}{M}, \sigma_B^2\right),$$

where M is the total number of ages.

- ▶ For the $\alpha_x^{(i)}$ and A_x ,

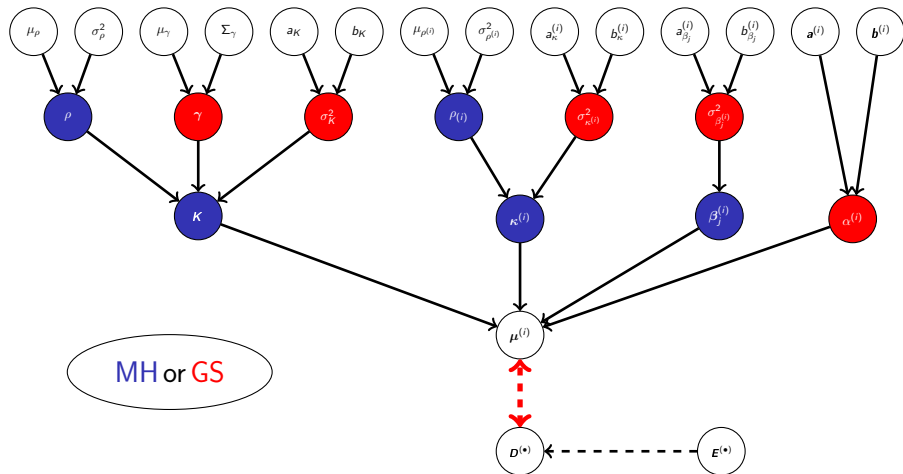
$$e_x^{(i)} = \exp\left(\alpha_x^{(i)}\right) \sim \mathcal{G}\left(a_x^{(i)}, b_x^{(i)}\right).$$

$$\mathcal{E}_x = \exp(A_x) \sim \mathcal{G}\left(a_x, b_x\right).$$

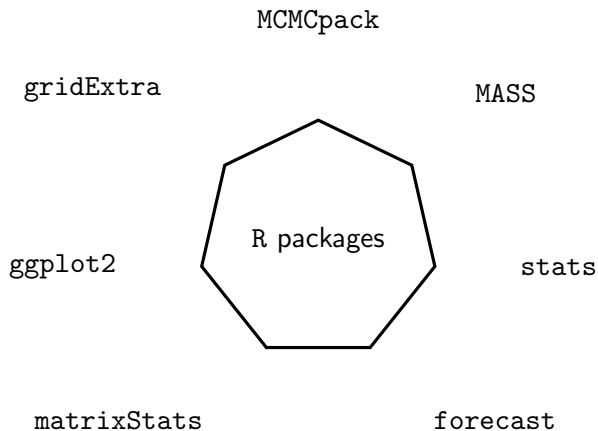
where $a_x^{(i)}$, $b_x^{(i)}$, a_x and b_x are constants.

- ▶ See our paper for prior assumptions on the hyperparameters.

Bayesian framework: MH and Gibbs Sampler for LC-2,t



R implementation



Contribution

- ▶ Full specification of MCMC.
- ▶ Two empirical studies including,
 - parameter estimates and uncertainty,
 - convergence checks,
 - mortality forecasts,
 - comparison to LL (SVD) and univariate LC.
- ▶ Official institutions (such as CBS, AG-AI or IA|BE) can use this model to challenge their point estimates obtained with MLE.

Empirical Studies

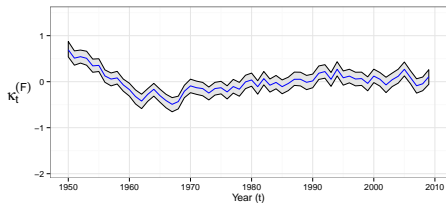
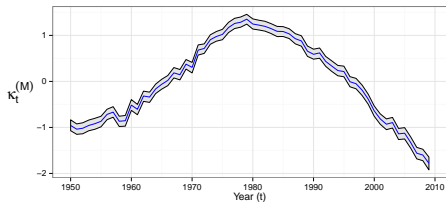
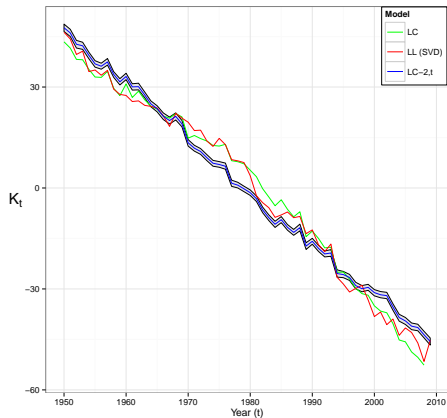
▶ Empirical study 1:

- Country: Sweden
- Gender: males & females,
- Time period: from 1950 until 2009,
- Age period: from 0 to 89.
- Studied also by Li & Lee (2005) and Hyndman et al. (2013).

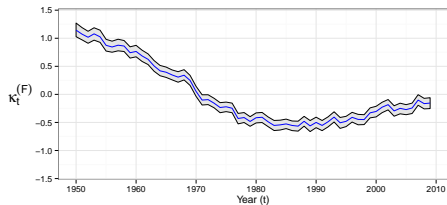
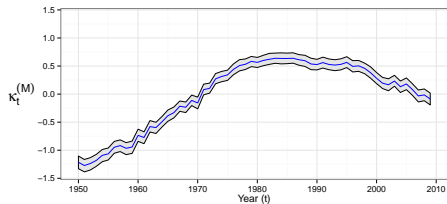
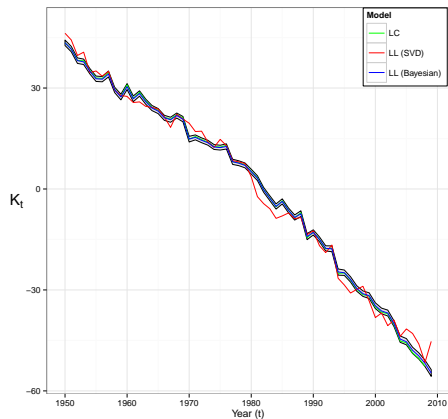
▶ Empirical study 2:

- Country: 14 countries,
- Gender: females,
- Time period: from 1975 until 2009,
- Age period: from 0 to 89.
- Studied also by AG-AI (2014) and Antonio, Devolder & Devriendt (2015).

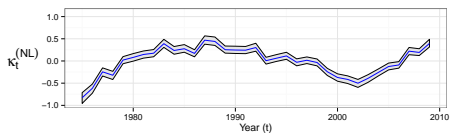
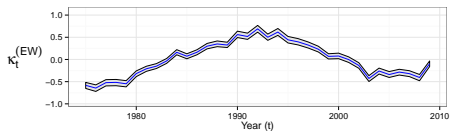
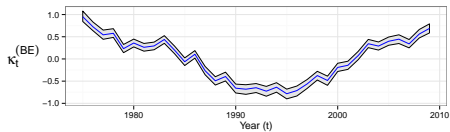
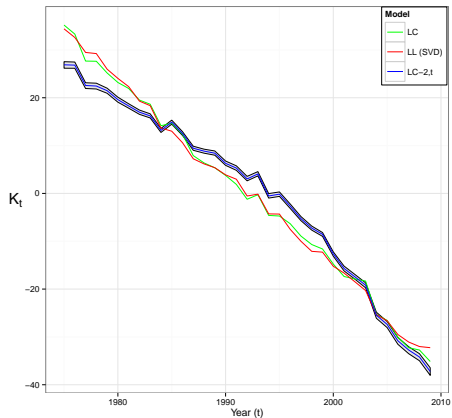
Empirical study: Sweden (LC-2,t model)



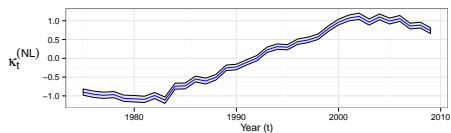
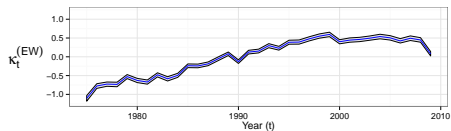
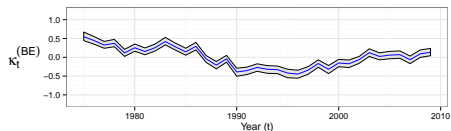
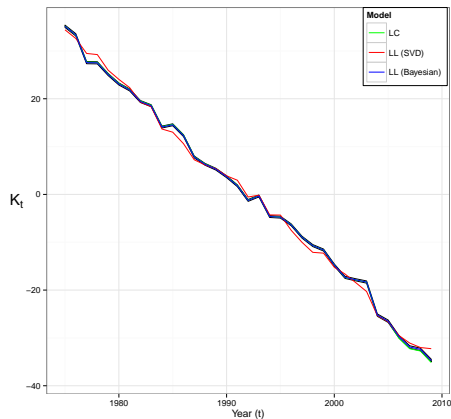
Empirical study: Sweden (LL model)



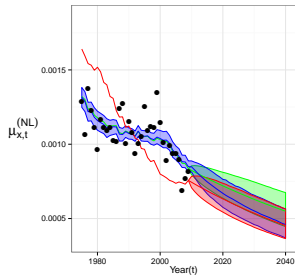
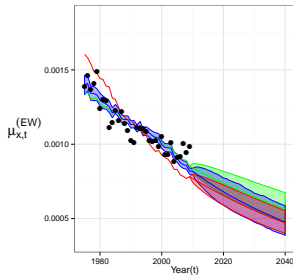
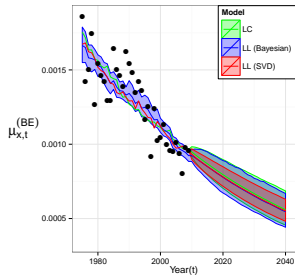
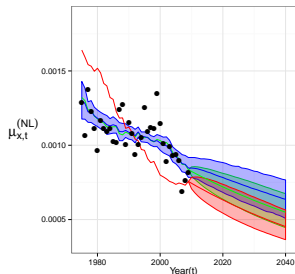
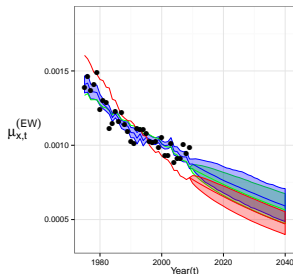
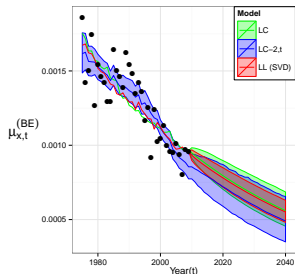
Empirical study: 14 countries (LC-2,t model)



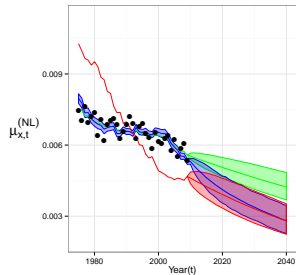
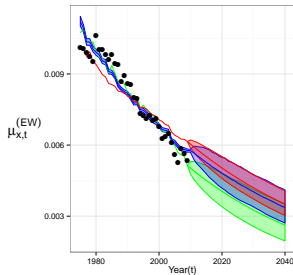
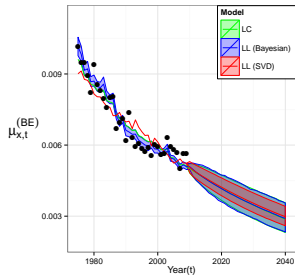
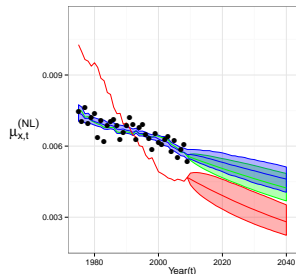
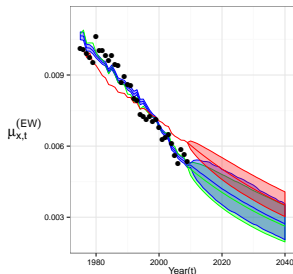
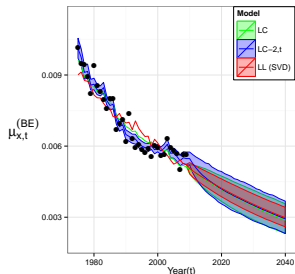
Empirical study: 14 countries (LL model)



14 countries: LC-2,t (top) and LL (bottom) at age 40



14 countries: LC-2,t (top) and LL (bottom) at age 60



Thanks for your time!

